MATH 1210

Attempt all questions and show all your work. Due December 7, 2015.

- 1. Let Q(1,3,-2) be a point in xyz-space,  $P_1: x y + 2z = 1$  and  $P_2: 2x + y + z = 4$  be two planes in xyz-space.
  - (a) Find an equation of the plane through Q that is parallel to  $P_1$ .

**Solution:** If the planes are parallel, then they have the same normal vector, so the normal to the plane we seek is (1, -1, 2) and the plane equation takes the form x - y + 2z = d, where the value of d is such that Q belongs to the plane. Substituting the coordinates of Q, i.e., (1, 3, -2), for (x, y, z), we have

$$(1) - (3) + 2(-2) = d \Leftrightarrow d = -6$$

and thus the equation we seek is x - y + 2z = -6.

(b) Find an equation of the plane through Q and perpendicular to the line of the intersection of  $P_1$  and  $P_2$ .

Solution: First, we seek the line of intersection of 
$$P_1$$
 and  $P_2$ :  

$$\begin{bmatrix} 1 & -1 & 2 & | & 1 \\ 2 & 1 & 1 & | & 4 \end{bmatrix} \xrightarrow{R_2 \leftarrow R_2 - 2R_1} \begin{bmatrix} 1 & -1 & 2 & | & 1 \\ 0 & 3 & -3 & | & 2 \end{bmatrix}$$

$$\stackrel{R_2 \leftarrow R_2/3}{\rightarrow} \begin{bmatrix} 1 & -1 & 2 & | & 1 \\ 0 & 1 & -1 & | & 2/3 \end{bmatrix} \xrightarrow{R_1 \leftarrow R_1 + R_2} \begin{bmatrix} 1 & 0 & 1 & | & 5/3 \\ 0 & 1 & -1 & | & 2/3 \end{bmatrix}.$$

Thus, for  $z = t \in \mathbb{R}$ , x = 5/3 - t and y = 2/3 + t, i.e., (x, y, z) = (-1, 1, 1)t + (5/3, 2/3, 0). The plane we seek is perpendicular to this line, i.e., has the direction of this line, (-1, 1, 1), as its normal vector. We can then proceed using the point normal form or, as we will, as in part (a): the plane we seek has equation -x + y + z = d and contains the point Q, so substituting the coordinates of Q gives us d:

 $-(1) + (3) + (-2) = d \Leftrightarrow d = 0.$ 

Thus the plane has equation -x + y + z = 0.

- 2. Let  $P_1 = (1, -1, 2)$ ,  $P_2 = (2, 0, 4)$  and  $P_3 = (4, 0, 3)$  be three points in xyz-space.
  - (a) Is the triangle determined by those points a right triangle? Explain your answer.

**Solution:** If the triangle is a right triangle, then two of  $\overrightarrow{P_1P_2}$ ,  $\overrightarrow{P_1P_3}$  and  $\overrightarrow{P_2P_3}$  must be perpendicular. We know that for two nonzero vectors  $a, b, a \perp b \Leftrightarrow a \cdot b = 0$ . We have

$$\overrightarrow{P_1P_2} = (1,1,2), \quad \overrightarrow{P_1P_3} = (3,1,1) \text{ and } \overrightarrow{P_2P_3} = (2,0,-1),$$

 $\mathbf{SO}$ 

$$\overrightarrow{P_1P_2} \cdot \overrightarrow{P_1P_3} = 3 + 1 + 2 = 6, \quad \overrightarrow{P_1P_2} \cdot \overrightarrow{P_2P_3} = 2 - 2 = 0 \quad \text{and} \quad \overrightarrow{P_1P_3} \cdot \overrightarrow{P_2P_3} = 6 - 1 = 5.$$

Thus  $\overrightarrow{P_1P_2} \perp \overrightarrow{P_1P_3}$  and the triangle  $P_1P_2P_3$  is a right triangle with right angle at  $P_3$ .

(b) Find an equation of the plane containing  $P_1$ ,  $P_2$  and  $P_3$ .

**Solution:** The normal to the plane we seek is perpendicular to the cross product of any pair of the vectors  $\overrightarrow{P_1P_2}$ ,  $\overrightarrow{P_1P_3}$  and  $\overrightarrow{P_2P_3}$ . We take for instance  $\overrightarrow{P_1P_2}$  and  $\overrightarrow{P_2P_3}$  [the latter has a zero coordinate that will make computations easier]:

$$\overrightarrow{P_1P_2} \times \overrightarrow{P_2P_3} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ 1 & 1 & 2 \\ 2 & 0 & -1 \end{vmatrix} = (-1, 5, -2).$$

Thus the plane has equation -x + 5y - 2z = d or, to get rid of some minus signs, x - 5y + 2z = e, where we seek the value of e by noting that the plane equation must hold for any of  $P_1$ ,  $P_2$  or  $P_3$ . Take  $P_2$ , for instance:

 $(2) - 5(0) + 2(4) = e \Leftrightarrow e = 6,$ 

so the equation of the plane is x - 5y + 2z = 6.

3. Find the inverse of the matrix or explain why the inverse does not exists.

(a)  $A = \begin{bmatrix} 1 & 2 & 3 \\ 2 & 5 & 3 \\ 1 & 0 & 8 \end{bmatrix}$ 

**Solution:** Compute det(A) by expanding along the bottom row:

$$\det(A) = \begin{vmatrix} 2 & 3 \\ 5 & 3 \end{vmatrix} + 8 \begin{vmatrix} 1 & 2 \\ 2 & 5 \end{vmatrix} = 6 - 15 + 40 - 32 = -1$$

so A is invertible. We compute the inverse using the adjugate. The matrix of cofactors is

$$C = \begin{bmatrix} 40 & -13 & -5\\ -16 & 5 & 2\\ -9 & 3 & 1 \end{bmatrix}$$

 $\mathbf{SO}$ 

$$A^{-1} = \frac{1}{\det(A)}C^{T} = \begin{bmatrix} -40 & 16 & 9\\ 13 & -5 & -3\\ 5 & -2 & -1 \end{bmatrix}.$$

(b) 
$$B = \begin{bmatrix} -1 & 3 & -4 \\ 2 & 4 & 1 \\ -4 & 2 & -9 \end{bmatrix}$$

Solution: We have

$$\det(B) = \begin{vmatrix} -1 & 3 & -4 \\ 2 & 4 & 1 \\ -4 & 2 & -9 \end{vmatrix} \begin{vmatrix} R_2 \leftarrow R_2 + 2R_1 \\ \equiv \\ R_3 \leftarrow R_3 - 4R_1 \end{vmatrix} \begin{vmatrix} -1 & 3 & -4 \\ 0 & 10 & -7 \\ 0 & -10 & 7 \end{vmatrix}$$

and thus det(B) = 0 since the third row is a multiple of the second (and thus adding, for instance, row 2 to row 3, would lead to a row of zeros). So B is not invertible.

4. Find all values of c, if any, for which the matrix  $A = \begin{bmatrix} c & 1 & 0 \\ 1 & c & 1 \\ 0 & 1 & c \end{bmatrix}$  is invertible.

**Solution:** A is invertible iff its determinant is nonzero. Expanding along, say, the first row, we find

$$\det(A) = c \begin{vmatrix} c & 1 \\ 1 & c \end{vmatrix} - \begin{vmatrix} 1 & 1 \\ 0 & c \end{vmatrix} = c(c^2 - 1) - c = c(c^2 - 2).$$

Therefore, A is invertible iff  $c \neq 0$  and  $c^2 - 2 \neq 0$ , i.e.,  $c \neq 0$ ,  $c \neq \sqrt{2}$  and  $c \neq -\sqrt{2}$ .

5. Show that if A is invertible, then  $det(A^{-1}) = det(A)^{-1}$ . Deduce a formula for the determinant of  $4A^{-1}$ , when A is an invertible  $n \times n$ -matrix.

**Solution:** If A is invertible, then  $A^{-1}$  exists such that  $AA^{-1} = I$ . Take the determinant of both sides and use the fact that det(AB) = det(A) det(B):

$$\det(AA^{-1}) = \det(I) \Leftrightarrow \det(A) \det(A^{-1}) = \det(I) \Leftrightarrow \det(A) \det(A^{-1}) = 1$$

and thus, dividing both sides of the latter equality by det(A),

$$\det(A^{-1}) = \det(A)^{-1}.$$

Recall that if all entries in a row of A are multiplied by some constant k, then the determinant of A is multiplied by k. So, if A is  $n \times n$ , if all entries of A are multiplied by k, then the determinant of A is multiplied by  $k^n$ . Therefore,

$$\det(4A^{-1}) = 4^n \det(A^{-1}) = \frac{4^n}{\det(A)}$$

6. Let

$$A = \begin{pmatrix} 1 & 0 & 1 \\ 4 & 1 & 2 \\ 0 & 3 & -1 \end{pmatrix} \quad \text{and} \quad B = \begin{pmatrix} 1 & 0 & 0 & 1 & -1 \\ 2 & 1 & 4 & 1 & 0 \\ -1 & 3 & 4 & 1 & 6 \end{pmatrix}.$$

Evaluate each of the following:

(a) The (2,3) cofactor of A.

Solution:  $c_{23} = -m_{23} = -3$ .

(b) The  $3^{rd}$  row of  $B^T A$ .

**Solution:** The third row of  $B^T A$  comes from multiplying the third row of  $B^T$  by the successive columns of A. We have

$$\begin{pmatrix} 0 & 4 & 4 \end{pmatrix} \begin{pmatrix} 1 & 0 & 1 \\ 4 & 1 & 2 \\ 0 & 3 & -1 \end{pmatrix} = \begin{pmatrix} 16 & 16 & 4 \end{pmatrix}.$$

(c)  $\det(2(A^{-1})^T)$ .

Solution: We have  $\det(2(A^{-1})^T) = 2^3 \det((A^{-1})^T) = 8 \det(A^{-1}) = 8/\det(A)$ and  $\det(A) = \begin{vmatrix} 1 & 2 \\ 3 & -1 \end{vmatrix} + \begin{vmatrix} 4 & 1 \\ 0 & 3 \end{vmatrix} = -7 + 12 = 5.$ Thus  $\det(2(A^{-1})^T) = 8/5.$ 

7. Writing the system

as  $A\mathbf{x} = \mathbf{b}$ ,

(a) find the inverse matrix  $A^{-1}$ ;

Solution: The matrix takes the form

$$A = \begin{bmatrix} 1 & 0 & 1 \\ 2 & 3 & 5 \\ 1 & 0 & 2 \end{bmatrix}$$

We compute the determinant by expanding along the second column:

$$\det(A) = 3 \begin{vmatrix} 1 & 1 \\ 1 & 2 \end{vmatrix} = 3,$$

so the matrix A is invertible. We invert it, for example, by row reduction. We have

$$[A|I] = \begin{bmatrix} 1 & 0 & 1 & | & 1 & 0 & 0 \\ 2 & 3 & 5 & | & 0 & 1 & 0 \\ 1 & 0 & 2 & | & 0 & 0 & 1 \end{bmatrix} \stackrel{R_2 \leftarrow R_2 - 2R_1}{R_3 \leftarrow R_3 - R_1} \begin{bmatrix} 1 & 0 & 1 & | & 1 & 0 & 0 \\ 0 & 3 & 3 & | & -2 & 1 & 0 \\ 0 & 0 & 1 & | & -1 & 0 & 1 \end{bmatrix}$$
$$\stackrel{R_1 \leftarrow R_1 - R_3}{\underset{R_2 \leftarrow R_2 - 3R_1}{\longrightarrow}} \begin{bmatrix} 1 & 0 & 0 & | & 2 & 0 & -1 \\ 0 & 3 & 0 & | & 1 & 1 & -3 \\ 0 & 0 & 1 & | & -1 & 0 & 1 \end{bmatrix} \stackrel{R_2 \leftarrow R_2 / 3}{\xrightarrow{\longrightarrow}} \begin{bmatrix} 1 & 0 & 0 & | & 2 & 0 & -1 \\ 0 & 1 & 0 & | & \frac{1}{3} & \frac{1}{3} & -1 \\ 0 & 0 & 1 & | & -1 & 0 & 1 \end{bmatrix} = [I|A^{-1}].$$

(b) find the solution to the system  $A^T \mathbf{x} = \mathbf{b}$  by using (a).

**Solution:** Since det(A) = det( $A^T$ ), the system  $A^T \mathbf{x} = \mathbf{b}$  has the unique solution  $\mathbf{x} = (A^T)^{-1}\mathbf{b}$ . Recall that  $(A^T)^{-1} = (A^{-1})^T$ . [Indeed, suppose A is invertible. Then  $A^T(A^{-1})^T = (A^{-1}A)^T = I^T = I$ , thus the inverse of  $A^T$  is  $(A^{-1})^T$ .] Thus  $\mathbf{x} = (A^T)^{-1}\mathbf{b} = (A^{-1})^T\mathbf{b} = \begin{bmatrix} 2 & 0 & -1 \\ \frac{1}{3} & \frac{1}{3} & -1 \\ -1 & 0 & 1 \end{bmatrix} \begin{bmatrix} 4 \\ -3 \\ 0 \end{bmatrix} = \begin{bmatrix} 8 \\ \frac{1}{3} \\ -4 \end{bmatrix}$ .

8. Let

$$A = \begin{bmatrix} 0 & 0 & 1 \\ 1 & 1 & 0 \\ 1 & 2 & 1 \end{bmatrix}$$

(a) Calculate det(A). Is A invertible? Explain.

Solution: Expanding along the top row, we get

$$\det(A) = \begin{vmatrix} 1 & 1 \\ 1 & 2 \end{vmatrix} = 1$$

so A is invertible since its determinant is nonzero.

(b) If A is invertible, find  $A^{-1}$  by using the row reduction method.

Solution: We have  

$$\begin{split} & [A|I] = \begin{bmatrix} 0 & 0 & 1 & | & 1 & 0 & 0 \\ 1 & 1 & 0 & | & 0 & 1 & 0 \\ 1 & 2 & 1 & | & 0 & 0 & 1 \end{bmatrix} \stackrel{R_1 \leftrightarrow R_2}{\rightarrow} \begin{bmatrix} 1 & 1 & 0 & | & 0 & 1 & 0 \\ 0 & 0 & 1 & | & 1 & 0 & 0 \\ 1 & 2 & 1 & | & 0 & 0 & 1 \\ 1 & 2 & 1 & | & 0 & 0 & 1 \\ 0 & 0 & 1 & | & 1 & 0 & 0 \end{bmatrix} \stackrel{R_2 \leftarrow R_2 - R_1}{\rightarrow} \begin{bmatrix} 1 & 1 & 0 & | & 0 & 1 & 0 \\ 0 & 1 & 1 & 0 & -1 & 1 \\ 0 & 0 & 1 & | & 1 & 0 & 0 \end{bmatrix} \stackrel{R_1 \leftarrow R_1 - R_2}{\rightarrow} \begin{bmatrix} 1 & 0 & 0 & | & 1 & 2 & -1 \\ 0 & 1 & 0 & | & -1 & -1 & 1 \\ 0 & 0 & 1 & | & 1 & 0 & 0 \end{bmatrix} \stackrel{R_1 \leftarrow R_1 - R_2}{\rightarrow} \begin{bmatrix} 1 & 0 & 0 & | & 1 & 2 & -1 \\ 0 & 1 & 0 & | & -1 & -1 & 1 \\ 0 & 0 & 1 & | & 1 & 0 & 0 \end{bmatrix} \stackrel{R_1 \leftarrow R_1 - R_2}{=} \begin{bmatrix} I & R_1 - R_1 - R_2 \\ 0 & 1 & 0 & | & 1 & 0 & 0 \end{bmatrix}$$

9. Let  $T : \mathbb{R}^3 \to \mathbb{R}^3$  be the linear transformation that reflects any vector about the *xz*-plane then multiplies its length by  $h \neq 0$ . Find the value of *h* so that the vector (2, 4, 3) is the image through *T* of the vector  $\left(-\frac{2}{3}, \frac{4}{3}, -1\right)$ .

**Solution:** First, the reflection about the *xz*-plane acts on  $\vec{i}, \vec{j}, \vec{k}$  as follows:  $T(\vec{i}) = \vec{i}$ ,  $T(\vec{j}) = -\vec{j}$  and  $T(\vec{k}) = \vec{k}$ . Multiplying the length of the image by *h* then results in the following action:  $T(\vec{i}) = h\vec{i}, T(\vec{j}) = -h\vec{j}$  and  $T(\vec{k}) = h\vec{k}$ . As a consequence, the matrix *A* associated to the linear transformation takes the form

$$A = \begin{bmatrix} h & 0 & 0 \\ 0 & -h & 0 \\ 0 & 0 & h \end{bmatrix}.$$

We are told that

$$(2,4,3) = T(-2/3,4/3,-1),$$

or, in other words,

$$A\begin{bmatrix} -\frac{2}{3}\\ \frac{4}{3}\\ -1\end{bmatrix} = \begin{pmatrix} 2\\ 4\\ 3 \end{pmatrix}$$

Thus

$$-\frac{2}{3}h = 2$$
$$-\frac{4}{3}h = 4$$
$$-h = 3,$$

so clearly, h = -3. [Which means that there is an additional reflection about the origin.]