MATH 1210 Assignment #4

Due: March 16, 2016; At the start of class

Reminder: all assignments must be accompanied by a signed copy of the honesty declaration available on the course website.

1. Find the line through (3, 1, -2) that intersects and is perpendicular to the line x = -1 + t, y = -2 + t, z = -1 + t with $t \in \mathbb{R}$.

Solution: To find the equation of the line L we need a point and a direction vector. We have a point (3, 1, -2); we have to find a direction vector \mathbf{v} . The line L is perpendicular to the line L_1 , which is passing through the point (-1, -2, -1) and having a direction vector $\langle 1, 1, 1 \rangle$, so \mathbf{v} is perpendicular to $\langle 1, 1, 1 \rangle$. The line L passes through (3, 1, -2) and intersects the line L_1 at a point P, so P is on L and also on L_1 . So P satisfies x = -1 + t, y = -2 + t, z = -1 + t with $t \in \mathbb{R}$; we need to find t corresponding to this point.

The vector starting at (3, 1, -2) and finishing at P is along the line L, so it is a direction vector for L: $\mathbf{v} = \langle 3 - (-1+t), 1 - (-2+t), -2 - (-1+t) \rangle = \langle 4 - t, 3 - t, -1 - t \rangle$. As \mathbf{v} is perpendicular to $\langle 1, 1, 1 \rangle$, we have

$$\langle 4-t, 3-t, -1-t \rangle \cdot \langle 1, 1, 1 \rangle = 4-t+3-t-1-t=6-3t=0$$

so t=2. Therefore, $\mathbf{v}=\langle 4-2,3-2,-1-2\rangle=\langle 2,1,-3\rangle$. Using (3,1,-2) and $\mathbf{v}=\langle 2,1,-3\rangle$ the parametric equations for L are

$$x = 3 + 2t,$$

 $y = 1 + 1t,$
 $z = -2 - 3t,$

and the symmetric equations are

$$\frac{x-3}{2} = y - 1 = \frac{-z-2}{3}.$$

2. Find an equation for the plane containing the two lines of equations

$$\langle x, y, z \rangle = \langle 0, 1, 2 \rangle + t_1 \langle 2, 3, -1 \rangle, \quad t_1 \in \mathbb{R}$$

and

$$\langle x, y, z \rangle = \langle 2, -1, 0 \rangle + t_2 \langle 4, 6, -2 \rangle, \quad t_2 \in \mathbb{R}.$$

Solution: To find the equation of a plane we need a point in the plane and its normal vector. We have 2 lines: L_1 passing through the point (0,1,2) and having as direction vector $\mathbf{v_1} = \langle 2, 3, -1 \rangle$ and L_2 passing through the point (2, -1, 0) and having as direction vector $\mathbf{v_2} = \langle 4, 6, -2 \rangle$. We note that L_1 and L_2 are parallel as their direction vectors are in the same direction, $2\mathbf{v_1} = \mathbf{v_2}$.

If we have 2 (non-parallel) vectors belonging to the plane by using their cross product we will obtain the vector normal to the plane. We have already one vector $\mathbf{v_1}$ (or $\mathbf{v_2}$); as a second vector we consider the vector starting from (0,1,2) (point of L_1) and finishing at (2,-1,0) (point of L_2). This vector $\langle 2-0,-1-1,0-2\rangle = \langle 2,-2,-2\rangle$ belongs to the plane as the 2 points belong to the plane. To find the normal vector to the plane, compute the cross product of $\langle 2,-2,-2\rangle$ and $\mathbf{v_1}$ (or $\mathbf{v_2}$):

$$\langle 2, -2, -2 \rangle \times \langle 2, 3, -1 \rangle = \begin{vmatrix} \vec{\mathbf{i}} & \vec{\mathbf{j}} & \vec{\mathbf{k}} \\ 2 & -2 & -2 \\ 2 & 3 & -1 \end{vmatrix} = \begin{vmatrix} -2 & -2 \\ 3 & -1 \end{vmatrix} \vec{\mathbf{i}} - \begin{vmatrix} 2 & -2 \\ 2 & -1 \end{vmatrix} \vec{\mathbf{j}} + \begin{vmatrix} 2 & -2 \\ 2 & 3 \end{vmatrix} \vec{\mathbf{k}}$$
$$= 8\vec{\mathbf{i}} - 2\vec{\mathbf{j}} + 10\vec{\mathbf{k}}$$

For the equation of the plane, we use the point (2, -1, 0) and the normal vector (8, -2, 10) and obtain

$$8(x-2) - 2(y+1) + 10z = 0.$$

3. Show that the lines $x-3=4t_1$, $y-4=t_1$, z-1=0 and $x+1=12t_2$, $y-7=6t_2$, $z-5=3t_2$ with $t_1,t_2 \in \mathbb{R}$ intersect, and find the point of intersection.

Solution: The line L_1 has a direction vector $\langle 4, 1, 0 \rangle$ and the line L_2 has a direction vector $\langle 12, 6, 3 \rangle$. The 2 direction vectors are not parallel (it is not possible to express one vector as a multiple of the other one).

An intersection point must satisfy both equations of L_1 and L_2 . From the equations of L_1 , we know that all points on L_1 must have z = 1. Using z = 1 and the equation for the z-coordinates of L_2 points $z - 5 = 3t_2$, we can characterize in a unique way the value for $t_2: z = 1 = 5 + 3t_2$ then $t_2 = -4/3$. Using $t_2 = -4/3$ in L_2 equations, we obtain the following point $(-1 + 12 \times (-4/3), 7 + 6 \times (-4/3), 1) = (-17, -1, 1)$ which belongs to L_2 . Check if this point (-17, -1, 1) belongs to L_1 (satisfies the L_1 equations):

$$-17 = 3 + 4t_1 \qquad \Rightarrow t_1 = -5$$

$$-1 = 4 + t_1 \qquad \Rightarrow t_1 = -5$$

$$1 = 1$$

Using $t_1 = -5$ in L_1 equations, we find (-17, -1, 1). Therefore, (-17, -1, 1) is a point of both lines L_1 and L_2 . Since the two lines are not parallel, the two lines must intersect and the intersection point is (-17, -1, 1).

4. Solve the linear system

$$AX = B$$

where $\mathbf{B}^{T} = [0, 0, 0]$ and

$$\mathbf{A} = \begin{bmatrix} 1 & -2 & 0 & 3 \\ 2 & -3 & -1 & -4 \\ 3 & -5 & -1 & -1 \end{bmatrix}$$

Specify the method used to solve the linear system.

Solution: The augmented matrix corresponding to the homogeneous system is

$$\begin{bmatrix} 1 & -2 & 0 & 3 & 0 \\ 2 & -3 & -1 & -4 & 0 \\ 3 & -5 & -1 & -1 & 0 \end{bmatrix} \quad R_2 \to R_2 - 2R_1, \ R_3 \to R_3 - 3R_1$$

$$\begin{bmatrix} 1 & -2 & 0 & 3 & 0 \\ 0 & 1 & -1 & -10 & 0 \\ 0 & 1 & -1 & -10 & 0 \end{bmatrix} \quad R_3 \to R_3 - R_2$$

$$\begin{bmatrix} 1 & -2 & 0 & 3 & 0 \\ 0 & 1 & -1 & -10 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} R_1 \to R_1 + 2R_2$$

The above matrix is the Row Echelon Form of the augmented matrix. If the Gaussian elimination method is used, stop the elementary row operations here and proceed to the back-substitutions in the system:

$$x_1 - 2x_2 + 3x_3 = 0$$
$$x_2 - x_3 - 10x_4 = 0$$

to find the solution. Otherwise, if Gauss-Jordan elimination is used, do the last elementary row operation $(R_1 \to R_1 + 2R_2)$ to obtain the Reduced Row Echelon Form of the augmented matrix

$$\begin{bmatrix} 1 & 0 & -2 & 23 & 0 \\ 0 & 1 & -1 & -10 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

The solution $\mathbf{X}^T = (x_1, x_2, x_3, x_4)$ is

$$x_1 = 2s + 23t,$$

$$x_2 = s + 10t,$$

$$x_3 = s, \quad s \in \mathbb{R},$$

$$x_4 = t, \quad t \in \mathbb{R},$$

or in basic solutions

$$\begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} = \begin{pmatrix} 2 \\ 1 \\ 1 \\ 0 \end{pmatrix} s + \begin{pmatrix} 23 \\ 10 \\ 0 \\ 1 \end{pmatrix} t, \quad s, t \in \mathbb{R}.$$

5. Compute the determinant of

(a)
$$\mathbf{A} = \begin{bmatrix} 1 & -2 & 0 & 3 \\ 2 & -3 & -1 & -4 \\ 3 & -5 & -1 & -1 \end{bmatrix}$$

(b)
$$\mathbf{A} = \begin{bmatrix} 1 & 0 & -1 & 2 \\ 2 & 1 & -3 & 4 \\ 0 & 2 & -2 & 3 \\ 1 & 1 & -4 & -2 \end{bmatrix}$$

- (c) \mathbf{A}^5 when \mathbf{A} is defined as in (b).
- (d) $-\mathbf{A}$ when \mathbf{A} is defined as in (b).
- (e) \mathbf{A}^T when \mathbf{A} is defined as in (b).

Solution:

- (a) A is not a square matrix. The determinant of A does not exist.
- (b) Before computing the determinant of **A** we will use row elementary operations on the matrix **A** to transform it to a triangular matrix.

$$\mathbf{A} = \begin{bmatrix} 1 & 0 & -1 & 2 \\ 2 & 1 & -3 & 4 \\ 0 & 2 & -2 & 3 \\ 1 & 1 & -4 & -2 \end{bmatrix} R_2 \to R_2 - 2R_1, R_4 \to R_4 - R_1$$

$$\begin{bmatrix} 1 & 0 & -1 & 2 \\ 0 & 1 & -1 & 0 \\ 0 & 2 & -2 & 3 \\ 0 & 1 & -3 & -4 \end{bmatrix} R_3 \to R_3 - 2R_2, R_4 \to R_4 - R_2$$

$$\begin{bmatrix} 1 & 0 & -1 & 2 \\ 0 & 1 & -1 & 0 \\ 0 & 0 & 0 & 3 \\ 0 & 0 & -2 & -4 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 & -1 & 2 \\ 0 & 1 & -1 & 0 \\ 0 & 0 & -2 & -4 \\ 0 & 0 & 0 & 3 \end{bmatrix}$$

Define
$$\mathbf{B} = \begin{bmatrix} 1 & 0 & -1 & 2 \\ 0 & 1 & -1 & 0 \\ 0 & 0 & -2 & -4 \\ 0 & 0 & 0 & 3 \end{bmatrix}$$
.

To obtain the upper-triangular matrix **B** from **A**, we used 4 additions of a nonzero multiple of one row to another row (operations that do not affect the determinant) and a single row interchange (operation that multiplies the determinant by -1). Hence, $\det(\mathbf{A}) = -\det(\mathbf{B})$.

As $\mathbf B$ is a upper-triangular matrix, the determinant of $\mathbf B$ is the product of the diagonal entries:

$$\det(\mathbf{B}) = 1 \times 1 \times (-2) \times 3 = -6.$$

Therefore, $det(\mathbf{A}) = 6$.

(c) $\mathbf{A}^5 = \mathbf{A} \times \mathbf{A} \times \mathbf{A} \times \mathbf{A} \times \mathbf{A}$. As the determinant of a product is the product of the determinant:

$$\det(\mathbf{A}^5) = \det(\mathbf{A})^5 = 6^5.$$

- (d) The matrix **A** is a 4×4 matrix, $\det(-\mathbf{A}) = (-1)^4 \det(\mathbf{A}) = 6$.
- (e) $\det(\mathbf{A}^{\mathbf{T}}) = \det(\mathbf{A}) = 6.$
- 6. Find all values of λ for which $\det(\mathbf{A}) = 0$ for $\mathbf{A} = \begin{bmatrix} \lambda 4 & 0 & 0 \\ 0 & \lambda & 2 \\ 0 & 3 & \lambda 1 \end{bmatrix}$.

Solution: Compute det(A):

$$\det(\mathbf{A}) = (\lambda - 4) \begin{vmatrix} \lambda & 2 \\ 3 & \lambda - 1 \end{vmatrix} = (\lambda - 4)(\lambda(\lambda - 1) - 6) = (\lambda - 4)(\lambda^2 - \lambda - 6)$$

To have $\det(\mathbf{A}) = 0$, we need to find the roots of $P(\lambda) = (\lambda - 4)(\lambda^2 - \lambda - 6) = 0$. The 3 roots of $P(\lambda)$ are

$$\lambda_1 = 4$$

$$\lambda_2 = \frac{1 - \sqrt{1 + 24}}{2} = -2$$

$$\lambda_3 = \frac{1 + \sqrt{1 + 24}}{2} = 3$$

Values of λ for which $det(\mathbf{A}) = 0$ are -2, 3 and 4.

7. Consider the following linear system

$$2x - y + 2z = 2,$$

 $x - y - z = 1,$
 $4x + 2y - z = 0.$

- (a) What is the rank of the augmented matrix of the linear system?
- (b) What is the rank of the coefficient matrix of the linear system?
- (c) By using Gauss-Jordan elimination, solve the linear system.

Solution: Consider the nonhomogeneous system AX = B. Transform the aug-

mented matrix [A|B] to its Reduced Row Echelon Form:

$$\begin{bmatrix} 2 & -1 & 2 & 2 \\ 1 & -1 & -1 & 1 \\ 4 & 2 & -1 & 0 \end{bmatrix} \quad R_1 \leftrightarrow R_2$$

$$\begin{bmatrix} 1 & -1 & -1 & 1 \\ 2 & -1 & 2 & 2 \\ 4 & 2 & -1 & 0 \end{bmatrix} \quad R_2 \to R_2 - 2R_1, R_3 \to R_3 - 4R_1$$

$$\begin{bmatrix} 1 & -1 & -1 & 1 \\ 0 & 1 & 4 & 0 \\ 0 & 6 & 3 & -4 \end{bmatrix} \quad R_1 \to R_1 + R_2, R_3 \to R_3 - 6R_2$$

$$\begin{bmatrix} 1 & 0 & 3 & 1 \\ 0 & 1 & 4 & 0 \\ 0 & 0 & -21 & -4 \end{bmatrix} \quad R_3 \to -R_3/21$$

$$\begin{bmatrix} 1 & 0 & 3 & 1 \\ 0 & 1 & 4 & 0 \\ 0 & 0 & 1 & 4/21 \end{bmatrix} \quad R_1 \to R_1 - 3R_3, R_2 \to R_2 - 4R_3$$

$$\begin{bmatrix} 1 & 0 & 0 & 9/21 \\ 0 & 1 & 0 & -16/21 \\ 0 & 0 & 1 & 4/21 \end{bmatrix}$$

- (a) There are 3 leading 1's in the Reduced Row Echelon Form of the augmented matrix, the rank of the augmented matrix is 3.
- (b) The 3 leading 1's are to the left of the vertical bar (the part corresponding to the coefficient matrix), so the rank of the coefficient matrix is 3.
- (c) The solution is

$$x = 9/21,$$

 $y = -16/21,$
 $z = 4/21.$

8. Consider the following linear system

$$2x_1 + 2x_2 - x_3 + x_5 = 0,$$

$$-x_1 - x_2 + 2x_3 - 3x_4 + x_5 = 0,$$

$$x_1 + x_2 - 2x_3 - x_5 = 0,$$

$$x_3 + x_4 + x_5 = 0.$$

(a) By using Gauss-Jordan elimination, solve the linear system.

- (b) Write your solution(s) using the basic solution(s).
- (c) Is the trivial solution a solution of this linear system? Explain your answer.

Solution: Transform the augmented matrix to its Reduced Row Echelon Form.

(a) The system has n=5 unknowns, the rank of the matrix is r=3, the solution

will be a n-r=5-3=2-parameter family. The solutions are

$$x_1 = -s - t$$

$$x_2 = s$$

$$x_3 = -t$$

$$x_4 = 0$$

$$x_5 = t$$

with $s, t \in \mathbb{R}$.

(b) Using basic solutions, the solutions are expressed as follows

$$\begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{pmatrix} = \begin{pmatrix} -1 \\ 1 \\ 0 \\ 0 \\ 0 \end{pmatrix} s + \begin{pmatrix} -1 \\ 0 \\ -1 \\ 0 \\ 1 \end{pmatrix} t, \quad s, t \in \mathbb{R}.$$
 (1)

(c) The trivial solution $\begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{pmatrix}$ is always solution to a homogeneous

system. For instance, take s = t = 0 in (1), the trivial solution is obtained.