

Vectors

Definition

Vectors are directed line segments.

Notation for vectors:

- ▶ by boldface type, e.g., \mathbf{v} ;
- ▶ by the initial and terminal points, e.g., OP ;
- ▶ by components, e.g., (x, y, z) , $\langle x, y, z \rangle$, $\begin{bmatrix} x \\ y \\ z \end{bmatrix}$.

Definition

The *length* of a vector $\mathbf{v} = \langle v_x, v_y, v_z \rangle$ is

$$|\mathbf{v}| = \sqrt{v_x^2 + v_y^2 + v_z^2}.$$

The length of $\mathbf{v} = \langle v_1, \dots, v_n \rangle$ is

$$|\mathbf{v}| = \sqrt{v_1^2 + \dots + v_n^2}.$$

If $|\mathbf{v}| = 1$ then \mathbf{v} is called a *unit vector*, denoted by $\hat{\mathbf{v}}$.

Let $\mathbf{u} = \langle u_1, \dots, u_n \rangle$ and $\mathbf{v} = \langle v_1, \dots, v_n \rangle$ be two vectors.

- ▶ Two vectors are equal if and only if they have the same length and direction, or if and only if they have the same components.
- ▶ Multiplication of a vector and a scalar:
$$\lambda \langle v_1, \dots, v_n \rangle = \langle \lambda v_1, \dots, \lambda v_n \rangle.$$
- ▶ Addition or subtraction of two vectors:
$$\langle u_1, \dots, u_n \rangle \pm \langle v_1, \dots, v_n \rangle = \langle u_1 \pm v_1, \dots, u_n \pm v_n \rangle.$$

Definition : Scalar/Dot/Inner Product of Vectors

Let $\mathbf{u} = \langle u_1, \dots, u_n \rangle$ and $\mathbf{v} = \langle v_1, \dots, v_n \rangle$ be two vectors. The dot product of \mathbf{u} and \mathbf{v} is

$$\mathbf{u} \cdot \mathbf{v} = u_1 v_1 + \dots + u_n v_n = \sum_{i=1}^n u_i v_i.$$

Properties of dot products:

- ▶ The dot product is **scalar** valued.
- ▶ $\mathbf{u} \cdot \mathbf{v} = \mathbf{v} \cdot \mathbf{u}$.
- ▶ $\mathbf{u} \cdot \mathbf{v} = \|\mathbf{u}\| \|\mathbf{v}\| \cos \theta$, where θ is the angle between \mathbf{u} and \mathbf{v} .
- ▶ $\mathbf{u} \cdot \mathbf{v} = 0$ if and only if \mathbf{u} and \mathbf{v} are orthogonal (in dimensions 2 and 3, we also say “perpendicular”).
- ▶ $\cos \theta = \frac{\mathbf{u} \cdot \mathbf{v}}{\|\mathbf{u}\| \|\mathbf{v}\|}$.

Definition : Vector/Cross/Outer Product

Let $\mathbf{u} = \langle u_x, u_y, u_z \rangle$ and $\mathbf{v} = \langle v_x, v_y, v_z \rangle$ be two vectors,
 $\vec{\mathbf{i}} = \langle 1, 0, 0 \rangle$, $\vec{\mathbf{j}} = \langle 0, 1, 0 \rangle$ and $\vec{\mathbf{k}} = \langle 0, 0, 1 \rangle$ be the *standard basis vectors*. Then

$$\mathbf{u} \times \mathbf{v} = \begin{vmatrix} \vec{\mathbf{i}} & \vec{\mathbf{j}} & \vec{\mathbf{k}} \\ u_x & u_y & u_z \\ v_x & v_y & v_z \end{vmatrix} = \begin{vmatrix} u_y & u_z \\ v_y & v_z \end{vmatrix} \vec{\mathbf{i}} - \begin{vmatrix} u_x & u_z \\ v_x & v_z \end{vmatrix} \vec{\mathbf{j}} + \begin{vmatrix} u_x & u_y \\ v_x & v_y \end{vmatrix} \vec{\mathbf{k}}$$

or

$$\mathbf{u} \times \mathbf{v} = (u_y v_z - u_z v_y) \vec{\mathbf{i}} + (u_z v_x - u_x v_z) \vec{\mathbf{j}} + (u_x v_y - u_y v_x) \vec{\mathbf{k}}$$

Properties of cross product:

- ▶ The cross product is **vector** valued.
- ▶ $\mathbf{u} \times \mathbf{v}$ is perpendicular to both \mathbf{u} and \mathbf{v} .
- ▶ $|\mathbf{u} \times \mathbf{v}| = |\mathbf{u}||\mathbf{v}| \sin \theta$, where θ is the angle between \mathbf{u} and \mathbf{v} .
- ▶ $\sin \theta = \frac{|\mathbf{u} \times \mathbf{v}|}{|\mathbf{u}||\mathbf{v}|}$

Theorem

The equation for the plane through the point (x_0, y_0, z_0) perpendicular to the vector $\langle A, B, C \rangle$ is

$$A(x - x_0) + B(y - y_0) + C(z - z_0) = 0.$$

The vector $\langle A, B, C \rangle$ is called a normal vector to the plane.

Theorem

Let L be the line through the point (x_0, y_0, z_0) in direction $\mathbf{v} = \langle v_x, v_y, v_z \rangle$. Then the vector equation for L is:

$$\mathbf{r} = \mathbf{r}_0 + t\mathbf{v},$$

or

$$\langle x, y, z \rangle = \langle x_0, y_0, z_0 \rangle + t\langle v_x, v_y, v_z \rangle.$$

The parametric equations for L are

$$x = x_0 + v_x t,$$

$$y = y_0 + v_y t,$$

$$z = z_0 + v_z t.$$

If none of v_x , v_y , and v_z is equal to zero, the line L has symmetric equations

$$\frac{x - x_0}{v_x} = \frac{y - y_0}{v_y} = \frac{z - z_0}{v_z}.$$