## Problems

**4.1** Given the following equation set

- (a) Solve for  $\phi_1$  and  $\phi_2$  simultaneously.
- (b) Solve for  $\phi_1$  and  $\phi_2$  by iteration. Use 0.0 as your initial guess for both  $\phi_1$  and  $\phi_2$  and show your results for the first 4 iterations.
- **4.2** Given the following equation set

- (a) Solve for  $\phi_1$  and  $\phi_2$  simultaneously.
- (b) Solve for  $\phi_1$  and  $\phi_2$  using Gauss-Seidel iteration. Use 0.0 as your initial guess for both  $\phi_1$  and  $\phi_2$  and show your results for the first 4 iterations.
- **4.3** Given the following equation set

- (a) Solve for  $\phi_1$  and  $\phi_2$  using Gauss-Seidel iteration. Use 2.0 as your initial guess for both  $\phi_1$  and  $\phi_2$  and show your results for the first 5 iterations.
- (b) Calculate the magnitude of the percentage change between the 5th and 4th iteration values from part (a) for each of  $\phi_1$  and  $\phi_2$ .
- (c) Solve for  $\phi_1$  and  $\phi_2$  simultaneously.
- **4.4** Given the following equation set

- (a) Solve for  $\phi_1$  and  $\phi_2$  graphically. Use quadrule paper for your graph. Clearly label the graph.
- (b) Solve for  $\phi_1$  and  $\phi_2$  by elimination of unknowns.
- (c) Check your answer from part (b) by substituting it back into the original equations.
- **4.5** Given the following system of equations:

$x_1$	$-3 x_2$	$+ 12 x_3$	=	269
$5 x_1$	$-13 x_2$	$+2 x_3$	=	379
$x_1$	$-14 x_2$		=	-45

- (a) Solve the system of equations using Gauss Elimination.
- (b) Solve the system of equations using the Gauss-Jordan method.
- (c) Solve the system of equations using the Gauss-Seidel method. Use an initial guess of  $x_1 = x_2 = x_3 = 0$  and stop iteration using  $\epsilon_s = 1\%$ .
- **4.6** Given the following system of equations:

$x_1$	$-12 x_2$	$+5 x_3$	=	16
$3 x_1$		$-2 x_3$	=	272
$x_1$	$-3 x_2$	$+10 x_{3}$	=	146

- (a) Solve the system of equations using Gauss Elimination.
- (b) Check your answer from part (a) by substituting it into the original equations.
- (c) Solve the system of equations using the Gauss-Seidel method. Use an initial guess of  $x_1 = x_2 = x_3 = 0$  and stop iteration using  $\epsilon_s = 1\%$ . Throughout your calculations, keep 5 significant figures.
- **4.7** Given the following system of equations:

- (a) Solve the system of equations using Gauss Elimination.
- (b) Set up and start to solve the system of equations using the Gauss-Seidel method. Do only <u>two iterations</u> (one iteration being one set of calculations of all four x values). Use an initial guess of  $x_1 = x_2 = x_3 = x_4 = 0$ . Throughout your calculations, keep 5 significant figures and calculate relative error.
- **4.8** Given the following set of equations:

- (a) Solve the system of equations using Gauss Elimination.
- (b) Set up and start to solve the system of equations using the Gauss-Seidel method. Do only <u>two iterations</u> (i.e. calculate all *x* values two times). Use an initial guess of  $x_1 = x_2 = x_3 = 0$ . Throughout your calculations, keep 5 significant figures and calculate relative error.
- **4.9** Given the following general three-point equation for *T<sub>i</sub>*:

$$(a_P)_i T_i = (a_W)_i T_{i-1} + (a_E)_i T_{i+1} + (b_P)_i$$

which can also be written as:

$$(-a_W)_i T_{i-1} + (a_P)_i T_i + (-a_E)_i T_{i+1} = (b_P)_i$$

the TDMA uses the following relationship

$$T_i = P_i T_{i+1} + Q_i$$

where

$$P_{i} = \frac{(a_{E})_{i}}{((a_{P})_{i} - (a_{W})_{i}P_{i-1})}$$

and

$$Q_{i} = \frac{(a_{W})_{i}Q_{i-1} + (b_{P})_{i}}{((a_{P})_{i} - (a_{W})_{i}P_{i-1})}$$

The starting conditions are:  $P_1 = \frac{(a_E)_1}{(a_P)_1}$  and  $Q_1 = \frac{(b_P)_1}{(a_P)_1}$ . For the following tri-diagonal matrix equation set:

$$\begin{bmatrix} 3 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -1 & 3 \end{bmatrix} \begin{pmatrix} T_1 \\ T_2 \\ T_3 \end{pmatrix} = \begin{bmatrix} 625 \\ 25 \\ 1225 \end{bmatrix}$$

- (a) Solve for  $P_i$  and  $Q_i$  for i = 1, 2, and 3.
- (b) Solve the set of equations for  $T_1$ ,  $T_2$ , and  $T_3$  using back substitution.
- (c) Check your answer from part (b) by substituting it back into the original equations.
- **4.10** Given the following general three-point equation for  $\phi_i$ :

$$(a_P)_i \phi_i = (a_W)_i \phi_{i-1} + (a_E)_i \phi_{i+1} + (b_P)_i$$

which can also be written as:

$$(-a_W)_i\phi_{i-1} + (a_P)_i\phi_i + (-a_E)_i\phi_{i+1} = (b_P)_i$$

the TDMA uses the following relationship

$$\phi_i = P_i \phi_{i+1} + Q_i$$

where

$$P_i = \frac{(a_E)_i}{[(a_P)_i - (a_W)_i P_{i-1}]}$$

and

$$Q_{i} = \frac{(a_{W})_{i}Q_{i-1} + (b_{P})_{i}}{[(a_{P})_{i} - (a_{W})_{i}P_{i-1}]}$$

The starting conditions are:  $P_1 = \frac{(a_E)_1}{(a_P)_1}$  and  $Q_1 = \frac{(b_P)_1}{(a_P)_1}$ . For the following tri-diagonal matrix equation set:

$$\begin{bmatrix} 3 & -2 & 0 & 0 \\ -1 & 2 & -1 & 0 \\ 0 & -1 & 2 & -1 \\ 0 & 0 & -2 & 3 \end{bmatrix} \begin{pmatrix} \phi_1 \\ \phi_2 \\ \phi_3 \\ \phi_4 \end{pmatrix} = \begin{bmatrix} 67 \\ -25 \\ 10 \\ -10 \end{bmatrix}$$

- (a) Solve for  $P_i$  and  $Q_i$  for i = 1, 2, 3, and 4.
- (b) Solve the set of equations for  $\phi_1$ ,  $\phi_2$ ,  $\phi_3$ , and  $\phi_4$  using back substitution.
- (c) Check your answer from part (b) by substituting it back into the original equations.