

Topic 3: Non-Spherical Disturbances

Our basic linear regression model is

$$y = X\beta + \varepsilon \quad ; \quad \varepsilon \sim N[\mathbf{0}, \sigma^2 I_n]$$

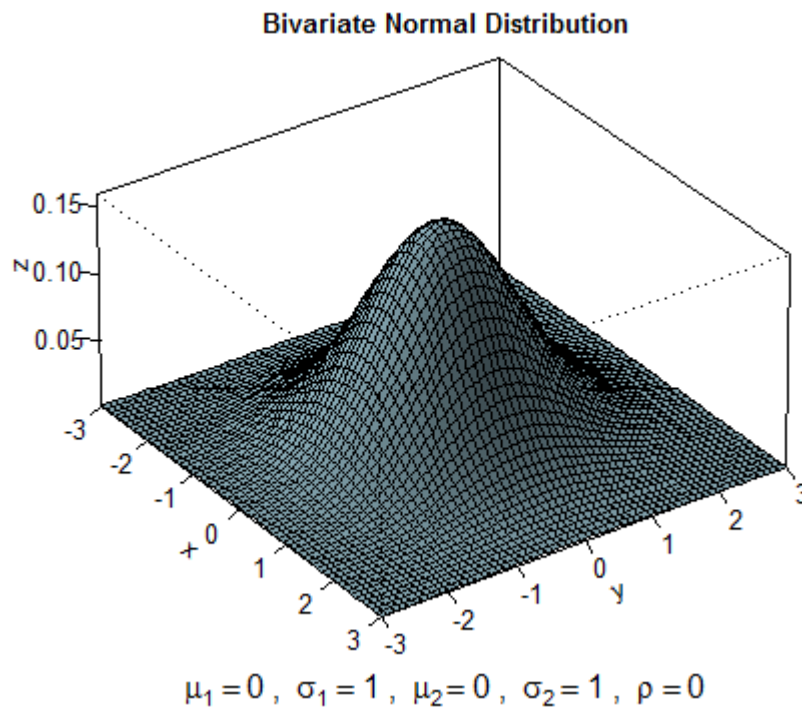
Now we'll generalize the specification of the error term in the model:

$$E[\varepsilon] = \mathbf{0} \quad ; \quad E[\varepsilon\varepsilon'] = \Sigma = \sigma^2\Omega \quad ; \quad (\& \text{ Normal})$$

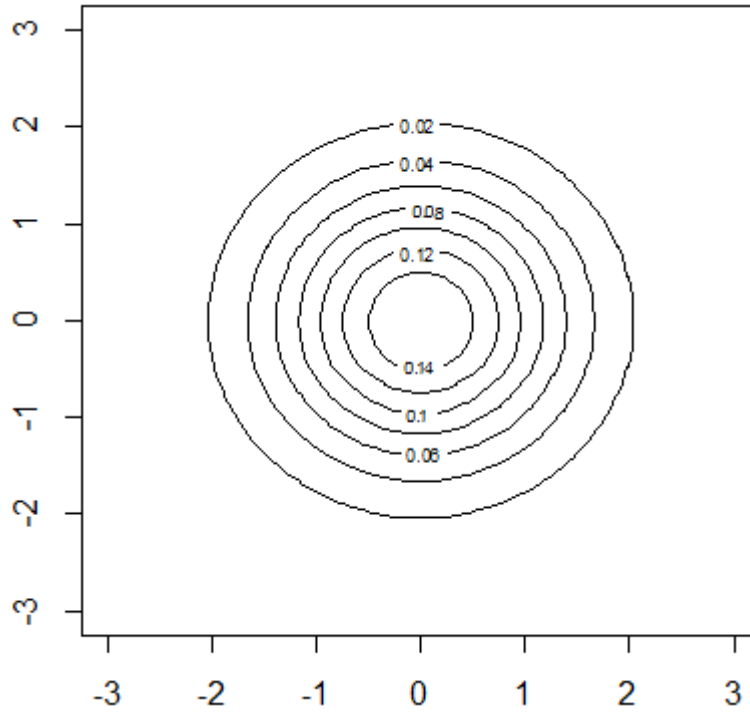
This allows for the possibility of one or both of

- Heteroskedasticity
- Autocorrelation (Cross-section; Time-series; Panel data)

Spherical Disturbances – Homoskedasticity and Non-Autocorrelation

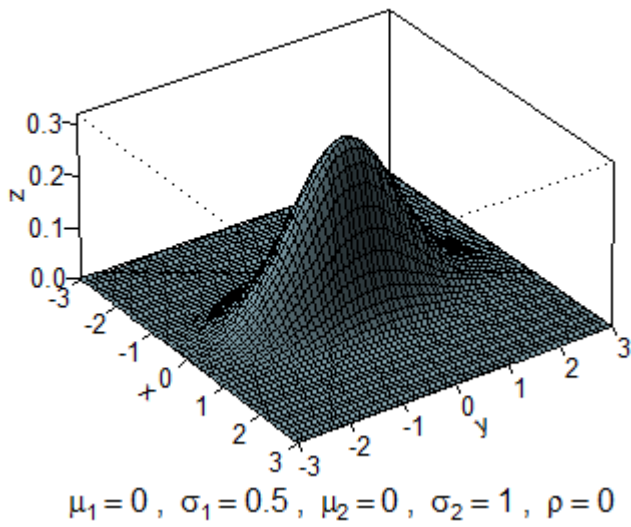


In the above, consider $x = \varepsilon_i$ and $y = \varepsilon_j$. The joint probability density function, $p(\varepsilon_i, \varepsilon_j)$, is in the direction of the z axis. Below is a contour of the above perspective. If we consider the joint distribution of *three* error terms instead of *two*, the circles below would become spheres, hence the terminology “spherical disturbances.”

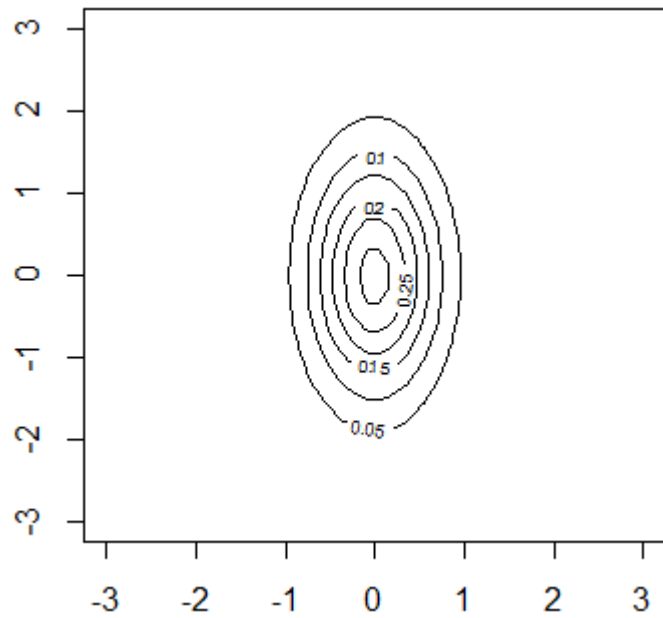


Non-Spherical Disturbances – Heteroskedasticity and Non-Autocorrelation

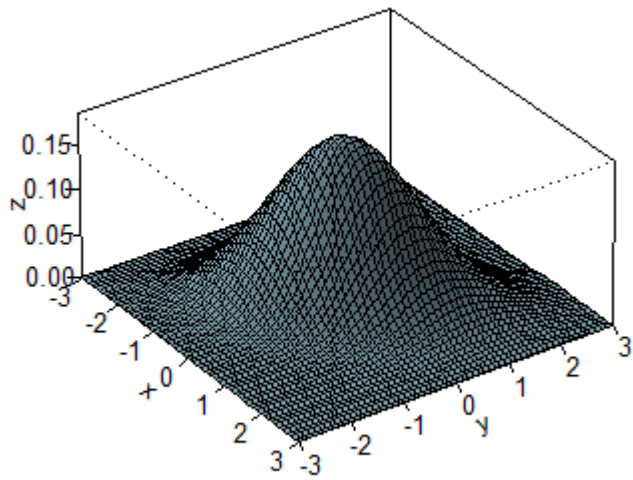
Bivariate Normal Distribution



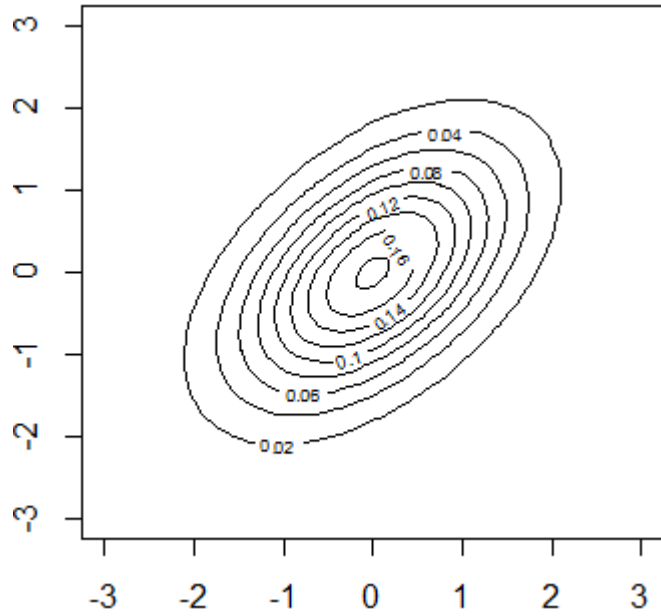
$\mu_1=0, \sigma_1=0.5, \mu_2=0, \sigma_2=1, \rho=0$



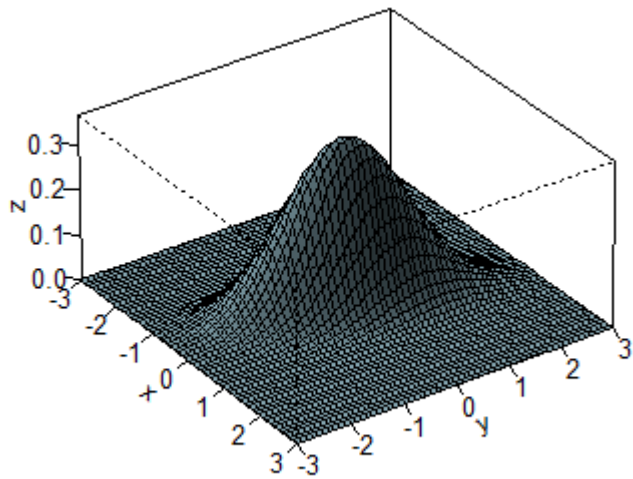
Non-Spherical Disturbances – Homoskedasticity and Autocorrelation



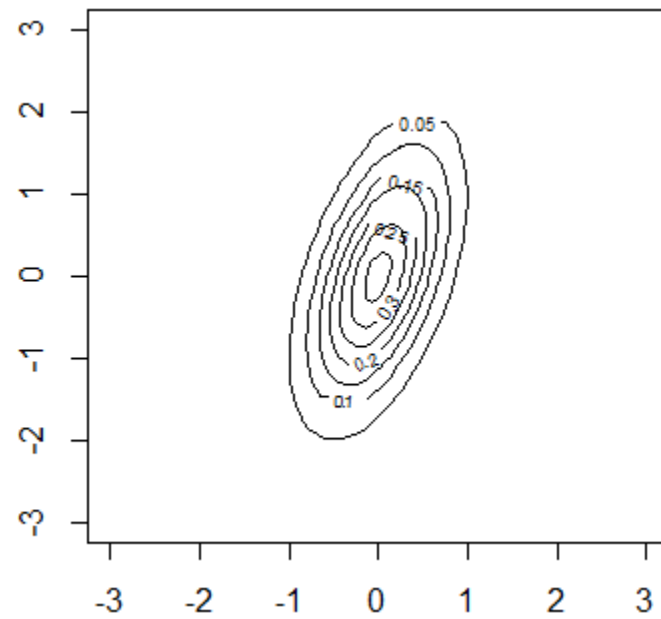
$\mu_1=0, \sigma_1=1, \mu_2=0, \sigma_2=1, \rho=0.5$



Non-Spherical Disturbances – Heteroskedasticity and Autocorrelation



$\mu_1=0, \sigma_1=0.5, \mu_2=0, \sigma_2=1, \rho=0.5$



How does the more general situation of non-spherical disturbances affect our (Ordinary) Least Squares estimator?

In particular, let's first look at the sampling distribution of \mathbf{b} :

$$\begin{aligned}\mathbf{b} &= (X'X)^{-1}X'\mathbf{y} = (X'X)^{-1}X'(X\boldsymbol{\beta} + \boldsymbol{\varepsilon}) \\ &= \boldsymbol{\beta} + (X'X)^{-1}X'\boldsymbol{\varepsilon}.\end{aligned}$$

So,

$$E(\mathbf{b}) = \boldsymbol{\beta} + (X'X)^{-1}X'E(\boldsymbol{\varepsilon}) = \boldsymbol{\beta}.$$

The more general form of the covariance matrix for the error term does not alter the fact that the OLS estimator is *unbiased*.

Next, consider the covariance matrix of our OLS estimator in this more general situation:

$$\begin{aligned}V(\mathbf{b}) &= V[\boldsymbol{\beta} + (X'X)^{-1}X'\boldsymbol{\varepsilon}] = V[(X'X)^{-1}X'\boldsymbol{\varepsilon}] \\ &= [(X'X)^{-1}X'V(\boldsymbol{\varepsilon})X(X'X)^{-1}] \\ &= [(X'X)^{-1}X'\sigma^2\Omega X(X'X)^{-1}] \\ &\neq [\sigma^2(X'X)^{-1}].\end{aligned}$$

So, under our full set of modified assumptions about the error term:

$$\mathbf{b} \sim N[\boldsymbol{\beta}, V^*]$$

where

$$V^* = \sigma^2[(X'X)^{-1}X'\Omega X(X'X)^{-1}].$$

- So, the usual computer output will be misleading, *numerically*, as it will be based on using the wrong formula, namely $s^2(X'X)^{-1}$.
- The standard errors, t-statistics, *etc.* will all be incorrect.
- As well as being *unbiased*, the OLS point estimator of $\boldsymbol{\beta}$ will still be *weakly consistent*.
- The I.V. estimator of $\boldsymbol{\beta}$ will still be *weakly consistent*.

- **However**, the usual estimator for the covariance matrix of \mathbf{b} , namely $s^2(X'X)^{-1}$, will be an *inconsistent estimator* of the true covariance matrix of \mathbf{b} !
- This has serious implications for inferences based on confidence intervals, tests of significance, *etc.*
- So, we need to know how to deal with these issues.
- This will lead us to some *generalized estimators*.
- First, let's deal with the most pressing issue – the inconsistency of the estimator for the covariance matrix of \mathbf{b} .

White's Heteroskedasticity-Consistent Covariance Matrix Estimator

- If we knew $\sigma^2\Omega$, then the “estimator” of the covariance matrix for \mathbf{b} would just be:

$$V^* = [(X'X)^{-1}X'\sigma^2\Omega X(X'X)^{-1}]$$

$$= \frac{1}{n} \left[\left(\frac{1}{n} X'X \right)^{-1} \left(\frac{1}{n} X' \sigma^2 \Omega X \right) \left(\frac{1}{n} X'X \right)^{-1} \right]$$

- Let $Q^* = \left(\frac{1}{n} X' \Sigma X \right) \quad (k \times k)$

$$= \frac{1}{n} \sum_{i=1}^n \sum_{j=1}^n \sigma_{ij} \mathbf{x}_i \mathbf{x}_j'$$

$$(k \times 1) \quad (1 \times k)$$

- In the case of *heteroskedastic errors*, things simplify, because $\sigma_{ij} = 0$, for $i \neq j$.

Then, we have

$$Q^* = \frac{1}{n} \sum_{i=1}^n \sigma_i^2 \mathbf{x}_i \mathbf{x}_i'$$

- White (1980) showed that if we define

$$S_0 = \frac{1}{n} \sum_{i=1}^n e_i^2 \mathbf{x}_i \mathbf{x}_i'$$

Then, $plim(S_0) = Q^*$.

- This means that we can estimate the model by OLS; get the associated residual vector, \mathbf{e} ; and then a consistent estimator of V^* , the covariance matrix of \mathbf{b} , will be:

$$\hat{V}^* = \frac{1}{n} \left[\left(\frac{1}{n} X'X \right)^{-1} \left(\frac{1}{n} \sum_{i=1}^n e_i^2 \mathbf{x}_i \mathbf{x}_i' \right) \left(\frac{1}{n} X'X \right)^{-1} \right]$$

or,

$$\hat{V}^* = n[(X'X)^{-1} S_0 (X'X)^{-1}] .$$

- \hat{V}^* is a **consistent estimator** of V^* , regardless of the (unknown) form of the heteroskedasticity.
- This includes **no heteroskedasticity** (i.e., homoscedastic errors).
- Newey & West produced a corresponding consistent estimator of V^* for when the errors possibly exhibit autocorrelation (of some unknown form).
- Note that the White and the Newey-West estimators modify just the estimated covariance matrix of \mathbf{b} – not \mathbf{b} itself.
- As a result, the t -statistics, F -statistic, etc., will be modified, but only in a manner that is appropriate *asymptotically*.
- So, if we have heteroskedasticity (or autocorrelation), whether we modify the covariance estimator or not, the usual test statistics will be unreliable **in finite samples**.
- Now let's turn to the estimation of β , taking account of the fact that the error term has a non-scalar covariance matrix.
- Using this information should enable us to improve the *efficiency* of the LS estimator of the coefficient vector.