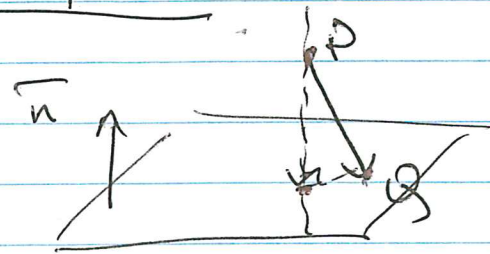


Sept. 19, 2019

#13, p. 740 Distance? From $(1, 3, 4)$ to plane $x+y-z=5$



$$\vec{n} = (1, 1, -2)$$

$$Q(5, 0, 0) \quad \{ P(1, 3, 4) \}$$

$$\vec{QP} = (-4, 3, 4)$$

$$\hat{n} = \frac{\vec{n}}{|\vec{n}|} = \frac{(1, 1, -2)}{\sqrt{1+1+4}} = \frac{1}{\sqrt{6}}(1, 1, -2)$$

$$\text{Dist} = |\vec{QP} \cdot \hat{n}| = \frac{1}{\sqrt{6}} |-4+3-8| = \frac{9}{\sqrt{6}}$$

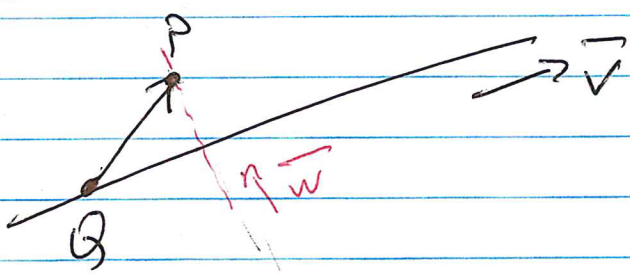
Formula
$$\text{Dist} = \frac{|Ax_0 + By_0 + Cz_0 + D|}{\sqrt{A^2 + B^2 + C^2}}$$

Eqn of plane: $x+y-z-5=0$

$$\text{Dist} = \frac{|1+3-2 \cdot 4 - 5|}{\sqrt{1+1+4}} = \frac{9}{\sqrt{6}}$$

#22, p. 741 Find dist from $(3, -2, 0)$ to the line $x=t, y=3-2t, z=4+t$.

Method 1:



$$P(3, -2, 0)$$

$$\vec{v} = (1, -2, 1)$$

$$Q(0, 3, 4) \quad \{ \text{set } t=0 \}$$

$$\vec{QP} = (3, -5, -4)$$

$$\vec{n}_1 = \vec{QP} \times \vec{v} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 3 & -5 & -4 \\ 1 & -2 & 1 \end{vmatrix} = (-13, -7, -1)$$

perpend. to plane
through P and containing
the line

Take $\vec{n} = (13, 7, 1)$ which is \parallel to \vec{n}_1 .

(3)

$$\vec{w}_1 = \vec{n} \times \vec{v} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 13 & 7 & 1 \\ 1 & -2 & 1 \end{vmatrix} = (9, -12, -33) = 3(3, -4, -11)$$

$\vec{w}_1 \perp$ line

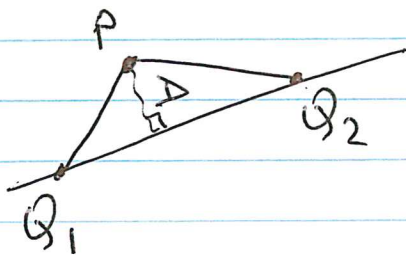
\vec{w}_1 is \parallel plane through P and containing the line.

Take $\vec{w} = (3, -4, -11)$ { note: $\vec{w} \parallel \vec{w}_1$ }

$$\hat{w} = \frac{\vec{w}}{|\vec{w}|} = \frac{(3, -4, -11)}{\sqrt{9+16+121}} = \frac{1}{\sqrt{146}} (3, -4, -11)$$

$$\text{Dist} = |\vec{QP} \cdot \hat{w}| = \frac{9+20+44}{\sqrt{146}} = \frac{73}{\sqrt{146}} = \sqrt{\frac{73}{2}}$$

Method 2:



$$\text{Area} = \frac{1}{2} |\vec{PQ}_1 \times \vec{PQ}_2|$$

$$= \frac{1}{2} |\vec{Q}_1\vec{Q}_2| \cdot \Delta$$

$$\therefore \Delta = \frac{|\vec{PQ}_1 \times \vec{PQ}_2|}{|\vec{Q}_1\vec{Q}_2|}$$

$$P(3, -2, 0)$$

$$\vec{PQ}_1 = (-3, 5, 4)$$

$$t=0: Q_1(0, 3, 4)$$

$$\vec{PQ}_2 = (-2, 3, 5)$$

$$t=1: Q_2(1, 1, 5)$$

$$\vec{Q}_1\vec{Q}_2 = (1, -2, 1)$$

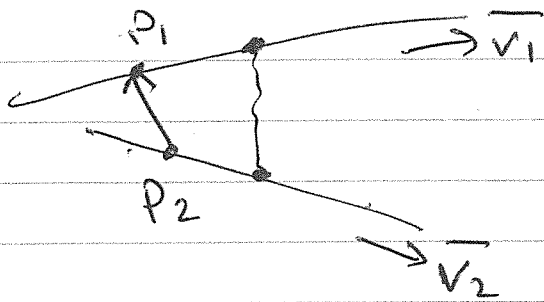
$$\vec{PQ}_1 \times \vec{PQ}_2 = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ -3 & 5 & 4 \\ -2 & 3 & 5 \end{vmatrix} = (13, 7, 1)$$

$$|\vec{PQ}_1 \times \vec{PQ}_2| = \sqrt{13^2 + 7^2 + 1^2} = \sqrt{169 + 49 + 1} = \sqrt{219}$$

$$|\vec{Q}_1\vec{Q}_2| = \sqrt{1+4+1} = \sqrt{6}$$

$$\therefore \Delta = \sqrt{\frac{219}{6}} = \sqrt{\frac{73}{2}}$$

Distance between 2 lines in 3D.



$\vec{v}_1 + \vec{v}_2 \perp$ both lines,

Dist = length of projection of $\overline{P_2 P_1}$ onto $\vec{v}_1 + \vec{v}_2$,

i.e., $dist = \left| \overline{P_2 P_1} \cdot \frac{\vec{v}_1 + \vec{v}_2}{|\vec{v}_1 + \vec{v}_2|} \right|$.

#26, p. 74 | Find dist. between the lines

$$\begin{cases} x = t \\ y = 3t - 1 \\ z = 1 + 2t \end{cases} \quad \text{and} \quad \begin{cases} x = 2 + t \\ y = 1 - t \\ z = 4 + 2t \end{cases}$$

Rewrite:

$$\begin{cases} x = 0 + t \\ y = -1 + 3t \\ z = 1 + 2t \end{cases} \quad \text{and} \quad \begin{cases} x = 1 + 2t \\ y = 1 - t \\ z = 4 + 2t \end{cases}$$

$$\vec{v}_1 = (1, 3, 2), \quad \vec{v}_2 = (2, -1, 2)$$

$$\vec{v}_1 + \vec{v}_2 = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 1 & 3 & 2 \\ 2 & -1 & 2 \end{vmatrix} = (8, 2, -7)$$

$$|\vec{v}_1 + \vec{v}_2| = \sqrt{8^2 + 2^2 + (-7)^2} = \sqrt{64 + 4 + 49} = \sqrt{117}$$

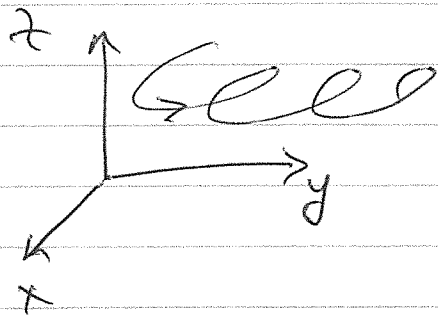
$$P_1(0, -1, 1), \quad P_2(1, 1, 4)$$

$$\overline{P_1 P_2} = (1, 2, 3)$$

$$\begin{aligned} Dist &= \left| (1, 2, 3) \cdot \frac{(8, 2, -7)}{\sqrt{117}} \right| = \frac{|8 + 4 - 21|}{\sqrt{117}} \\ &= \frac{9}{\sqrt{117}} = \frac{9}{\sqrt{3 \cdot 39}} = \frac{9}{3\sqrt{13}} = \frac{3}{\sqrt{13}} \end{aligned}$$

HW: p. 741 : # 11, 18, 19, 24, 31, 33.

sect. 11.9: Differentiation / Integration of vectors.



position vector of
a particle in 3D space at
time t : $(x(t), y(t), z(t))$.

$$\vec{r}(t) = (x(t), y(t), z(t)).$$

{ vector valued fcn: $\vec{r}: \mathbb{R} \rightarrow \mathbb{R}^3$ }

$$\vec{r}(t) = (x(t), y(t), z(t))$$

$$= x(t) \cdot \vec{i} + y(t) \cdot \vec{j} + z(t) \cdot \vec{k}, \quad a \leq t \leq b.$$

Facts: 1) $\lim_{t \rightarrow t_0} \vec{r}(t) = \left(\lim_{t \rightarrow t_0} x(t), \lim_{t \rightarrow t_0} y(t), \lim_{t \rightarrow t_0} z(t) \right)$
(def., etc.)

2) $\vec{r}(t)$ is continuous at t_0 if

$$\vec{r}(t_0) = \lim_{t \rightarrow t_0} \vec{r}(t) \quad (\text{definition})$$

3) $\vec{r}(t) = (x(t), y(t), z(t))$ is continuous at t_0
iff x, y, z are all continuous as fns of t .

4) Derivative:

$$\vec{r}'(t_0) = \lim_{h \rightarrow 0} \frac{\vec{r}(t_0+h) - \vec{r}(t_0)}{h}$$

provided this limit exists.

5) If $\vec{r}(t) = (x(t), y(t), z(t))$, then

$$\vec{r}'(t) = (x'(t), y'(t), z'(t)).$$

$\left\{ \begin{array}{l} \vec{r} \text{ is differentiable iff each component} \\ \text{is differentiable} \end{array} \right\}$

6) A vector valued fun $\vec{v}(t)$ is an antiderivative of $\vec{r}(t)$ on the interval $[a, b]$ if

$$\frac{d\vec{v}(t)}{dt} = \vec{r}(t) \text{ for all } t \in (a, b).$$

Theorem: If $f(t)$ is a differentiable real fun and $\vec{v}(t)$ and $\vec{u}(t)$ are diff. vector-valued fns,

then

$$1) \frac{d}{dt} (f(t) \vec{v}(t)) = \frac{df}{dt} \vec{v} + f \frac{d\vec{v}}{dt}$$

$$\left\{ = \frac{df}{dt}(t) \vec{v}(t) + f(t) \frac{d\vec{v}}{dt}(t) \right\}$$

$$2) \frac{d}{dt} (\vec{u} \cdot \vec{v}) = \frac{d}{dt} \vec{u} \cdot \vec{v} + \vec{u} \cdot \frac{d}{dt} \vec{v}$$

$$3) \frac{d}{dt} (\vec{u} \times \vec{v}) = \frac{d\vec{u}}{dt} \times \vec{v} + \vec{u} \times \frac{d\vec{v}}{dt}$$

Ex:

$$\vec{u} = (t, t^2, \sin t)$$

$$\vec{v} = (1, e^t, t), \quad t \in \mathbb{R}.$$

$$f(t) = t^3.$$

$$1) \frac{d}{dt} [f(t) \vec{v}(t)] = \frac{d}{dt} [t^3 (1, e^t, t)] =$$

1st approach

$$\textcircled{=} \frac{d}{dt} [(t^3, t^3 e^t, t^4)] =$$

$$= (3t^2, 3t^2 e^t + t^3 e^t, 4t^3).$$

2nd approach

$$\textcircled{=} \frac{dt^3}{dt} (1, e^t, t) + t^3 \frac{d}{dt} [(1, e^t, t)]$$

$$= 3t^2 (1, e^t, t) + t^3 (0, e^t, 1)$$

$$= (3t^2, 3t^2 e^t + t^3 e^t, 4t^3).$$

$$2) \frac{d}{dt} (\vec{u} \cdot \vec{v}) = \frac{d}{dt} [(t, t^2, \sin t) \cdot (1, e^t, t)]$$

$$= \frac{d}{dt} (t + t^2 e^t + t \sin t) =$$

$$= 1 + 2t e^t + t^2 e^t + \sin t + t \cos t.$$

Hw: 2nd approach using the above theorem.

Ex: $\vec{u}(t) = t \vec{i} - t^2 \vec{j} + \cos t \vec{k}$

Find $\int \vec{u}(t) dt$.

$$\int \vec{u}(t) dt = \int (t \vec{i} - t^2 \vec{j} + \cos t \vec{k}) dt =$$

$$= \left(\int t dt \right) \vec{i} - \left(\int t^2 dt \right) \vec{j} + \left(\int \cos t dt \right) \vec{k}$$

$$= \left(\frac{t^2}{2} + C_1 \right) \vec{i} - \left(\frac{1}{3} t^3 + C_2 \right) \vec{j} + \left(\sin t + C_3 \right) \vec{k}$$

$$= \frac{t^2}{2} \vec{i} - \frac{1}{3} t^3 \vec{j} + \sin t \vec{k} + \vec{c}, \text{ where}$$

\vec{c} is a constant vector.

2nd way to write:

$$\int \vec{u}(t) dt = \int (t, -t^2, \cos t) dt =$$

$$= \left(\int t dt, -\int t^2 dt, \int \cos t dt \right) =$$

$$= \left(\frac{1}{2} t^2 + C_1, -\frac{1}{3} t^3 + C_2, \sin t + C_3 \right)$$

$$= \left(\frac{1}{2} t^2, -\frac{1}{3} t^3, \sin t \right) + \vec{C}, \text{ where}$$

$$\vec{C} = (C_1, C_2, C_3) \left\{ \text{constant vector in } \mathbb{R}^3 \right\}$$

Section 11.10 Parametric and vector representation of curves.

Defn: A curve in 3D space is defined as

$$C: x = x(t), y = y(t), z = z(t), \alpha \leq t \leq \beta.$$

or

$$C: \vec{r}(t) = (x(t), y(t), z(t)), \alpha \leq t \leq \beta.$$

$$\vec{r}(t) = x(t)\vec{i} + y(t)\vec{j} + z(t)\vec{k}, \alpha \leq t \leq \beta.$$

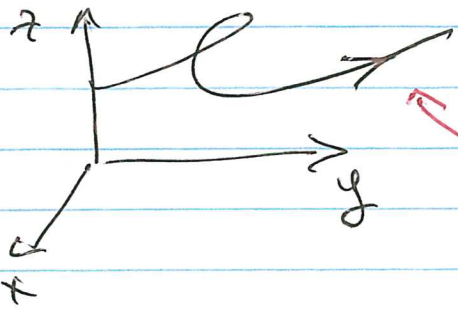
Note: A curve C given by

$$\vec{r}(t) = (x(t), y(t), z(t)), \alpha \leq t \leq \beta$$

is continuous iff $\vec{r} = \vec{r}(t)$ is continuous

iff $x(t), y(t)$ and $z(t)$ are all continuous for $\alpha \leq t \leq \beta$.

Orientation of curves:



$$r(t) = (x(t), y(t), z(t))$$

direction of movement as t increases.

#1, p. 765.
$$\begin{cases} x + 2y + 3z = 6 \\ y - 2z = 3 \end{cases}$$

Find vector representation for this curve directed so that $z \uparrow$ along the curve.

$$\begin{cases} y = 2z + 3 \\ x + 2(2z + 3) + 3z = 6 \end{cases} \quad (=) \quad \begin{cases} y = 2z + 3 \\ x = -7z \end{cases}$$

$$\begin{cases} x + 4z + 6 + 3z = 6 \\ x + 7z = 0 \end{cases}$$

$$\begin{cases} x = -7t \\ y = 3 + 2t \\ z = t \end{cases}, t \in \mathbb{R}.$$

(z is \uparrow as $t \uparrow$).