

# Chapter 1. Introduction

## This course consists of three parts

1. Finite element formulation
2. Discretization techniques
3. Computer implementation of FEM

## Where the course fits

The field of mechanics is divided into three parts

*Theoretical*

*Applied*

***Computational***

Computational mechanics can be distinguished according to the physical focus of attention

*Particle*

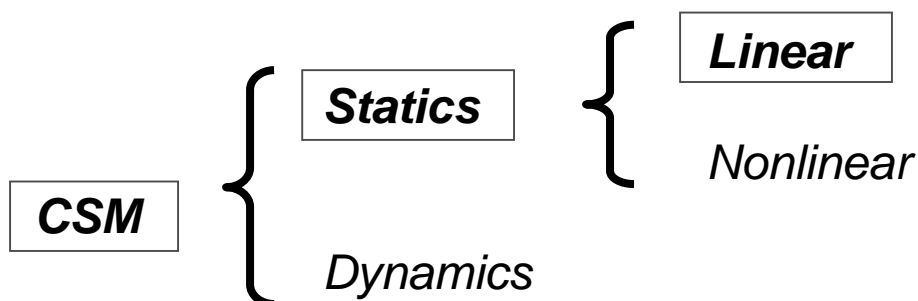
*Micromechanics*

***Solids and structure***

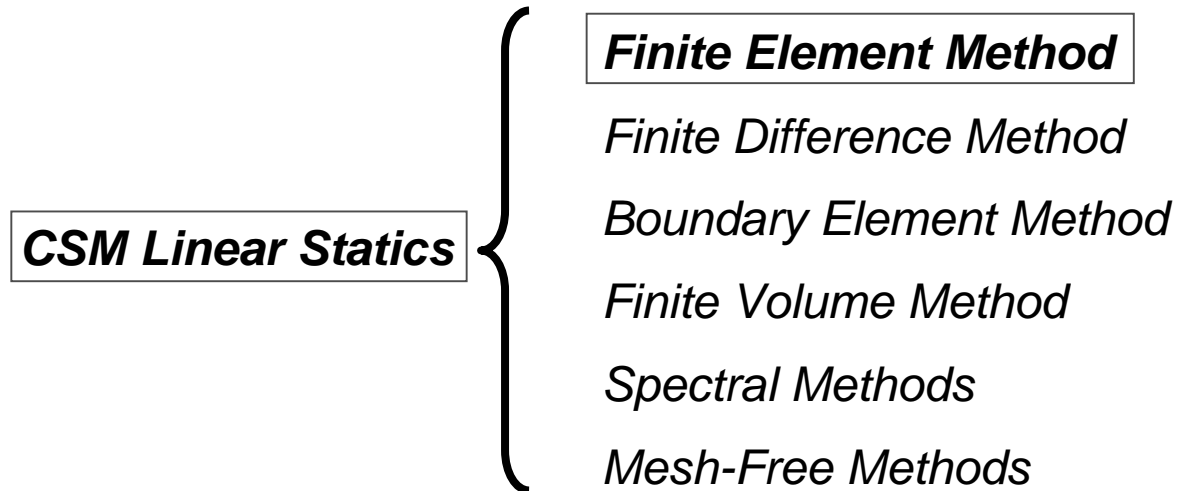
*Fluids*

*Coupled systems*

## Computational Solid and Structural Mechanics (CSM)

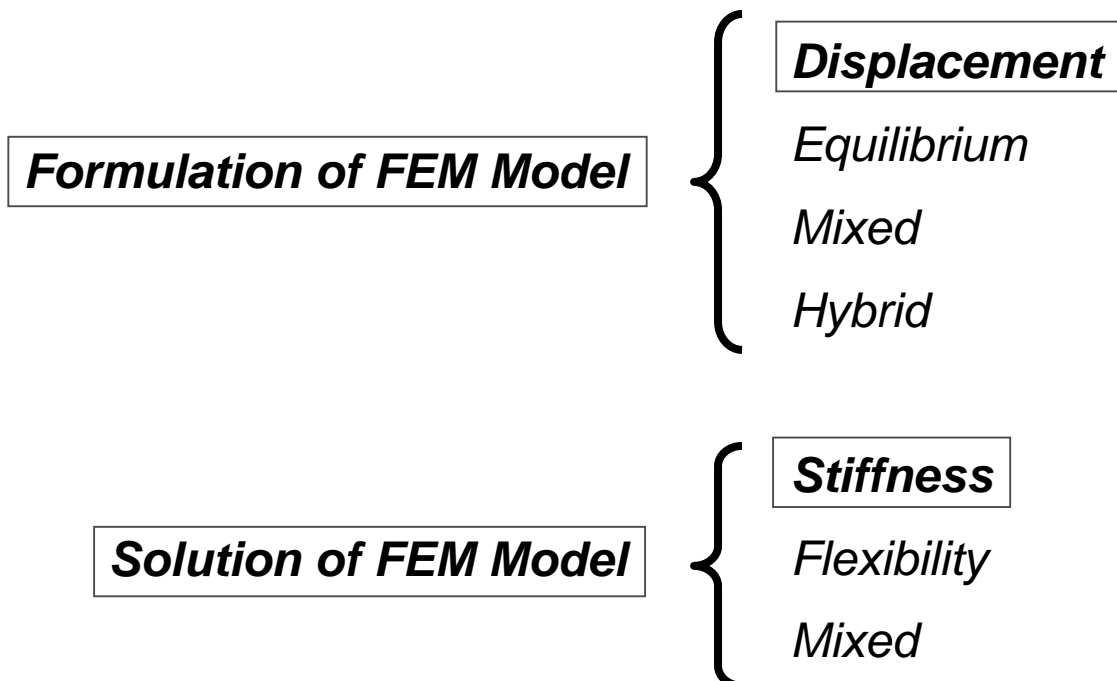


For the numerical simulation on the computer we must now choose **a spatial discretization method:**



## CSM Linear Statics by FEM

Having selected the FEM for discretization, we must next pick a formulation and a solution method:



# Summary: This Course Covers

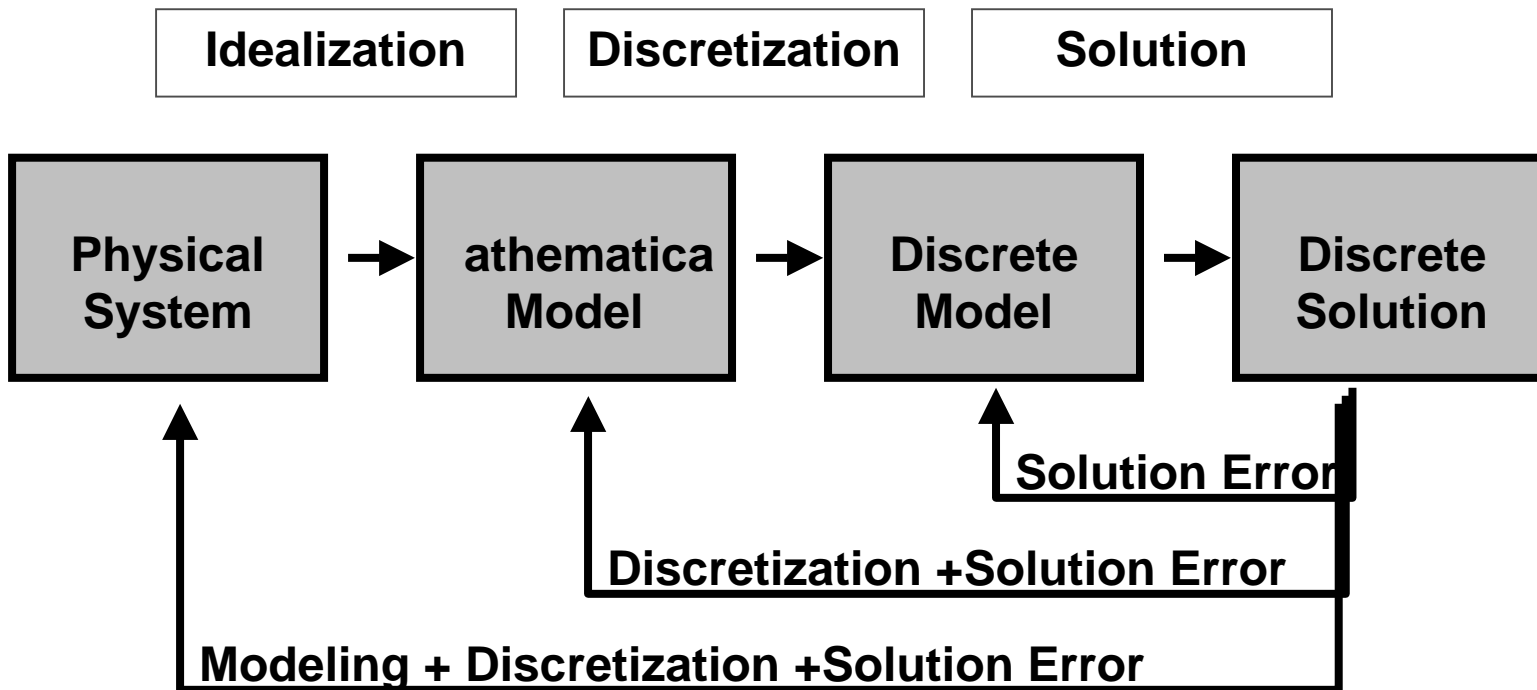
Computational Structural mechanics

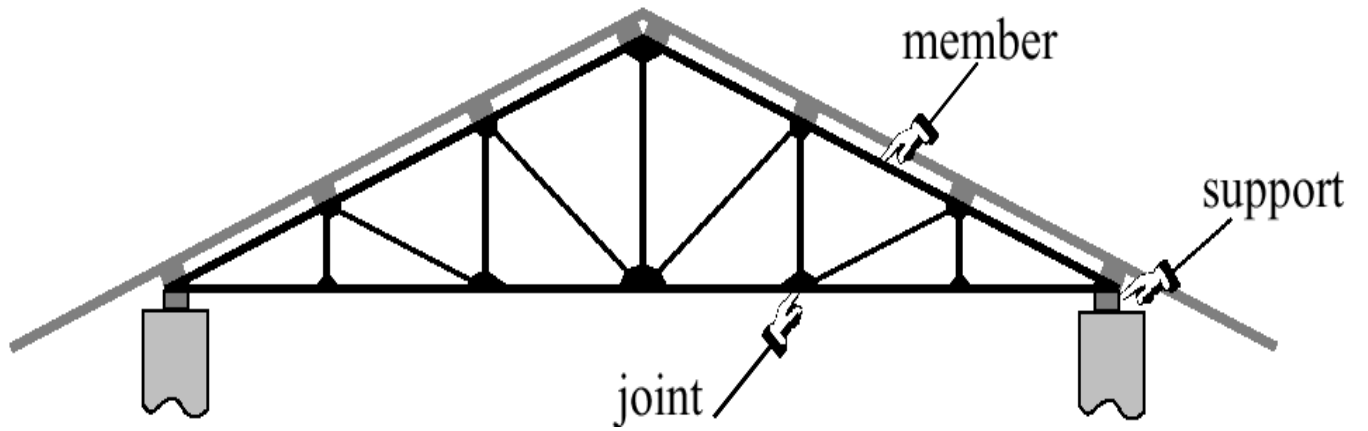
Linear statics problems

Spatially discretized by displacement-formulation FEM

Solved by stiffness method

## *Role of FEM*



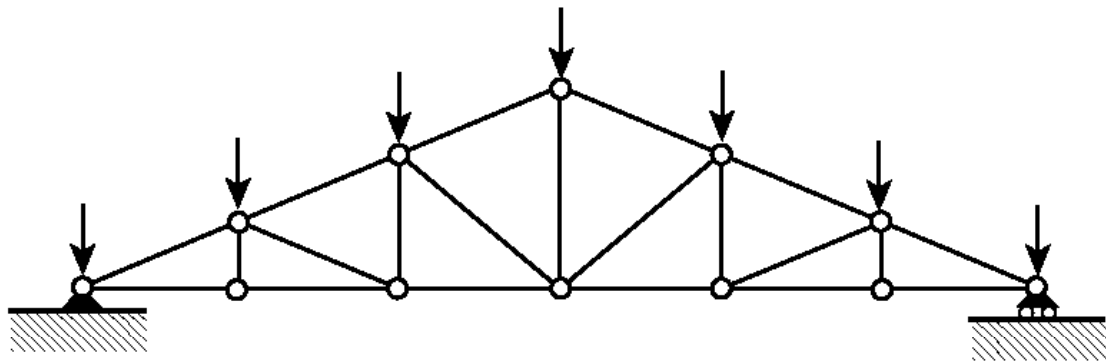


**Physical Model**



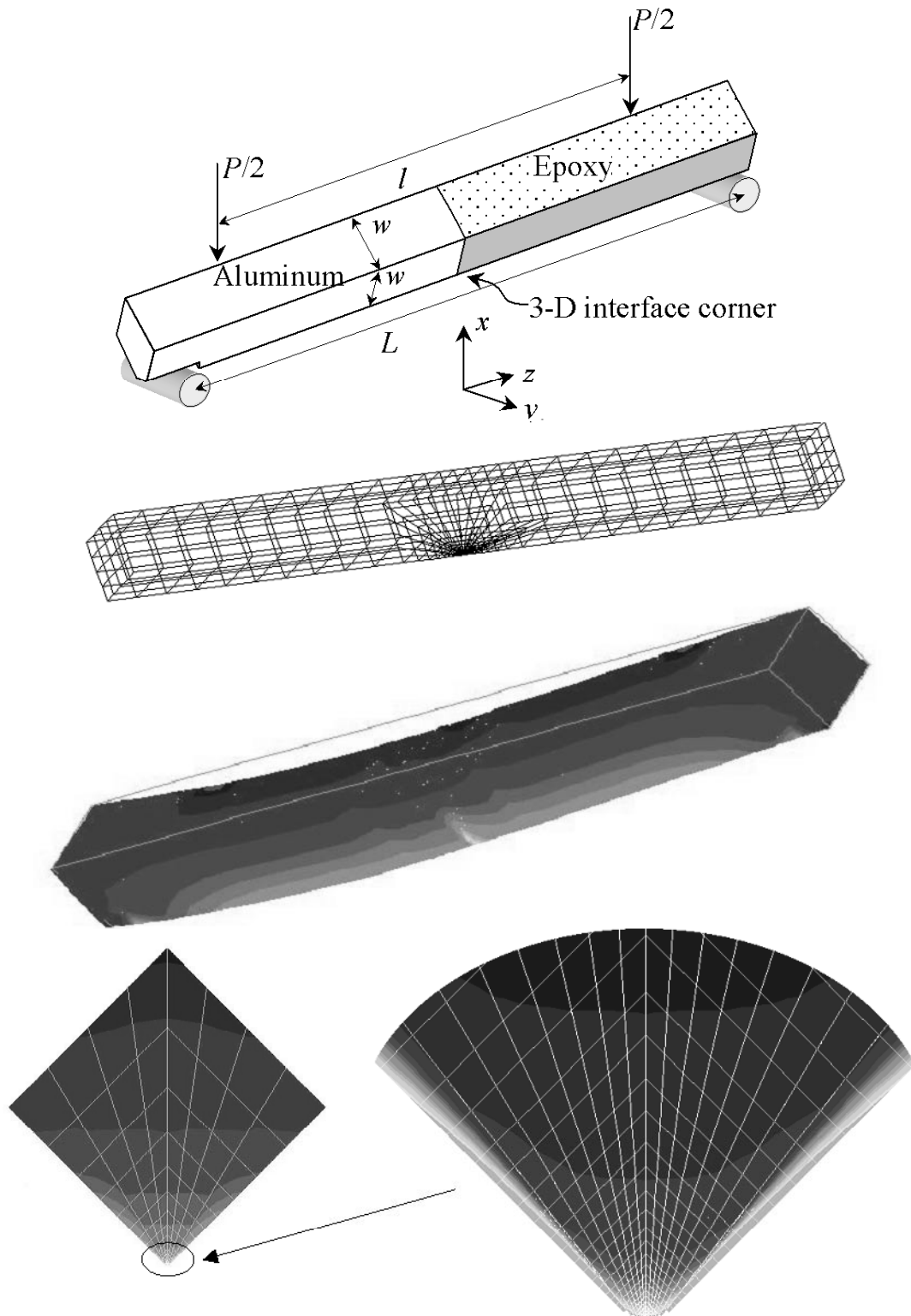
**Idealization**

**Mathematical Model**

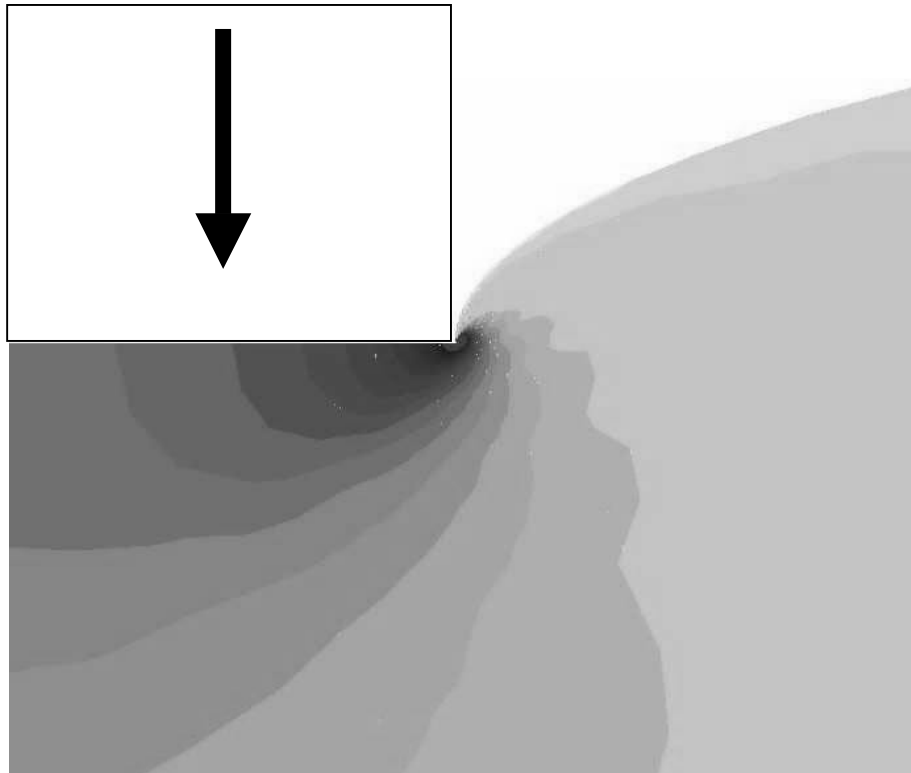


# EXAMPLES

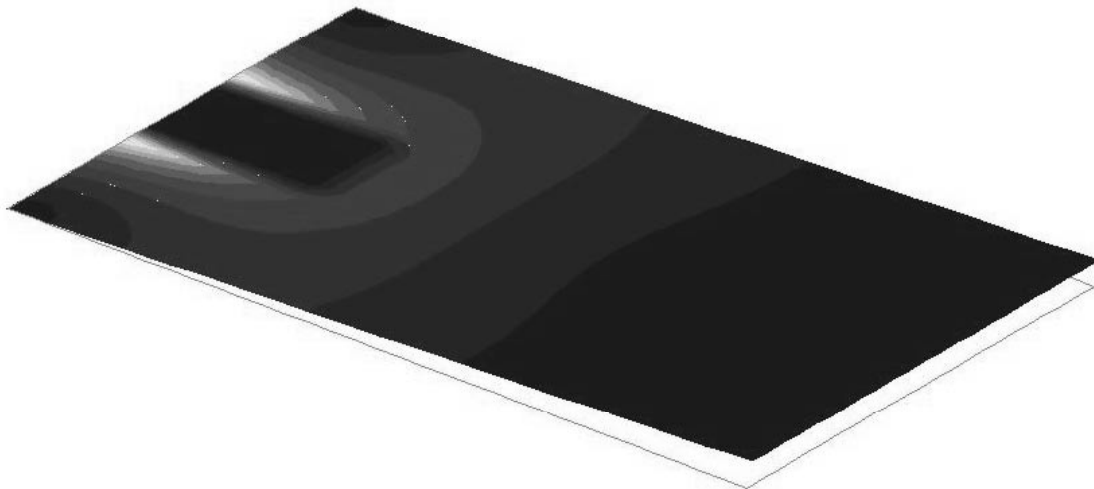
## ALUMINUM/EPOXY BIMATERIAL SPECIMEN IN BENDING



## RIGID PUNCH ON AN ELASTO-PLASTIC SUBSTRATE

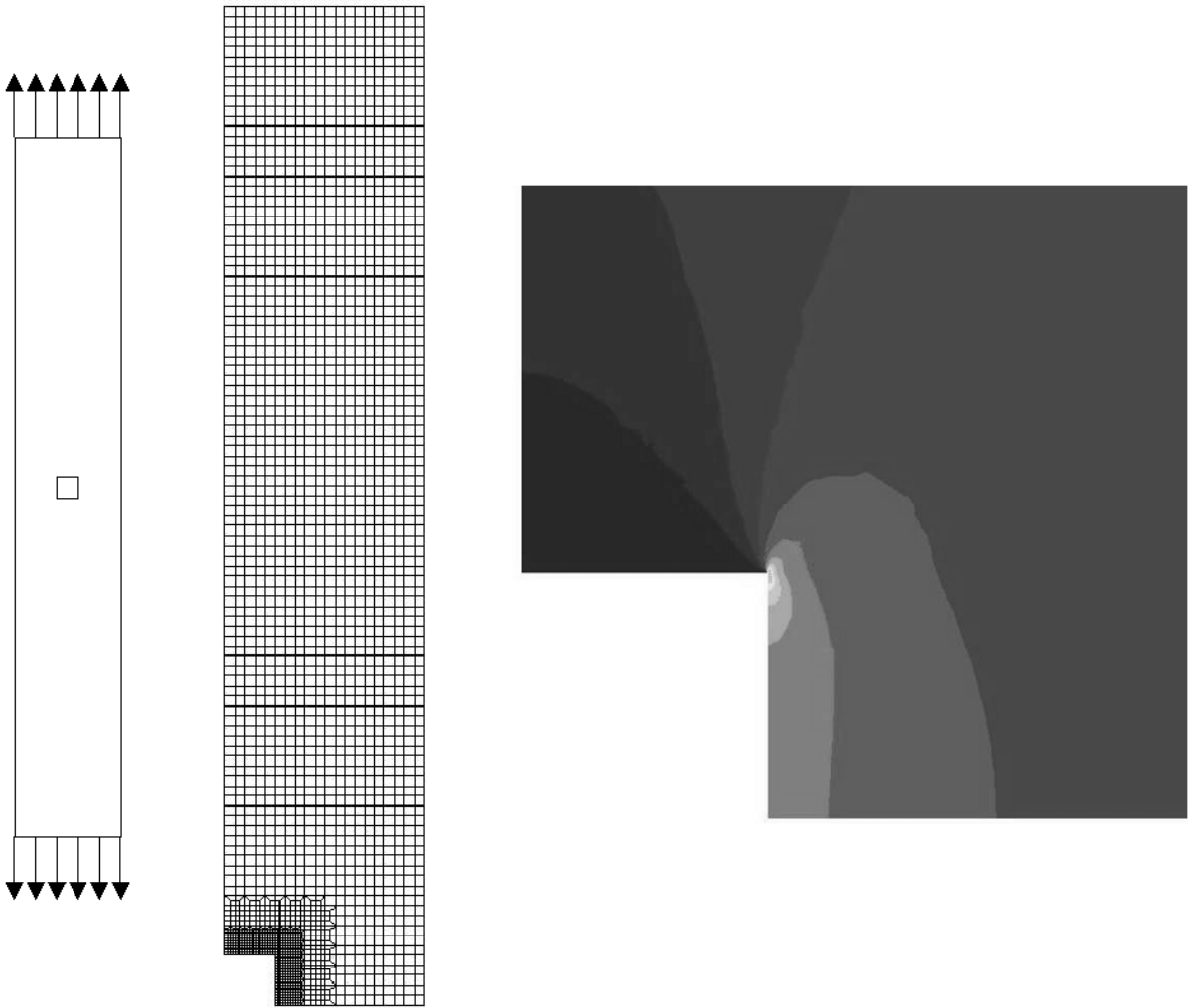


## THERMAL INDUCED DEFORMATION OF A MICRO MIRROR



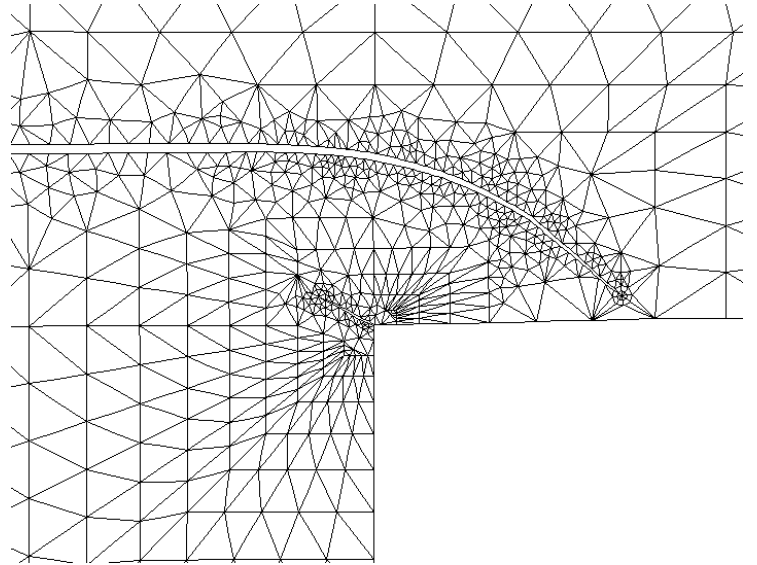
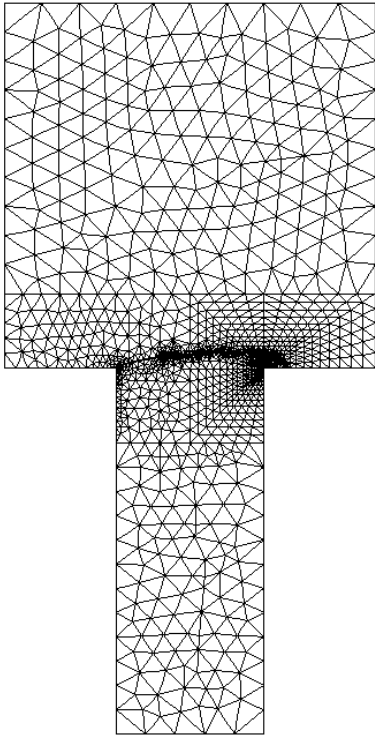
# SINGLE CRYSTAL SILICON PLATE WITH SQUARE HOLE

## LOADED IN TENSION



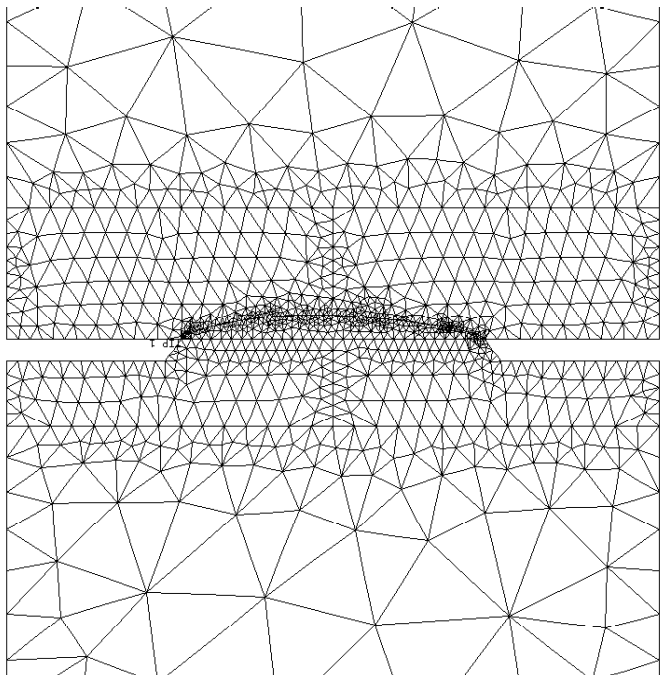
# CRACK PROPAGATION OF A PMMA T-STRUCTURE SPECIMEN

LOADED IN TENSION



# CRACK KINKING AND PROPAGATION IN A SILICON/GLASS

MICRO ACCELEROMETER PACKAGE





## WHAT NOT TO DO

