

ME 478 FINITE ELEMENT METHOD

Chapter 6.25 Flowchart to Compute K

Step 1 Decide what Gaussian Rule you want to use

(i.e. s_i , t_i and W_i)

Step 2 Calculate the shape functions and their derivatives

$$N_a(s_i, t_i), \frac{\partial N_a(s_i, t_i)}{\partial s}, \text{ and } \frac{\partial N_a(s_i, t_i)}{\partial t} \quad \begin{matrix} i = 1, 2, \dots, n_{\text{int}} \\ a = 1, 2, \dots, n_{\text{node}} \end{matrix}$$

Step 3 Calculate the Jacobian matrix and the Jacobian

$$\frac{\partial x}{\partial s} = \sum_{a=1}^{n_{\text{node}}} \frac{\partial N_a(s_i, t_i)}{\partial s} x_a, \quad \frac{\partial y}{\partial s} = \sum_{a=1}^{n_{\text{node}}} \frac{\partial N_a(s_i, t_i)}{\partial s} y_a$$

$$\frac{\partial x}{\partial t} = \sum_{a=1}^{n_{\text{node}}} \frac{\partial N_a(s_i, t_i)}{\partial t} x_a, \quad \frac{\partial y}{\partial t} = \sum_{a=1}^{n_{\text{node}}} \frac{\partial N_a(s_i, t_i)}{\partial t} y_a$$

$$|J(s_i, t_i)| = \det \begin{bmatrix} \frac{\partial x}{\partial s} & \frac{\partial x}{\partial t} \\ \frac{\partial y}{\partial s} & \frac{\partial y}{\partial t} \end{bmatrix} = \frac{\partial x}{\partial s}(s_i, t_i) \frac{\partial y}{\partial t}(s_i, t_i) - \frac{\partial x}{\partial t}(s_i, t_i) \frac{\partial y}{\partial s}(s_i, t_i)$$

Step 4 Calculate the derivatives of the shape functions w.r.t. the global coordinate system at the Gauss points

$$\frac{\partial N_a(s_i, t_i)}{\partial x} = \frac{1}{|J(s_i, t_i)|} \left(\frac{\partial N_a(s_i, t_i)}{\partial s} \frac{\partial y}{\partial t}(s_i, t_i) - \frac{\partial N_a(s_i, t_i)}{\partial t} \frac{\partial y}{\partial s}(s_i, t_i) \right)$$

$$\frac{\partial N_a(s_i, t_i)}{\partial y} = \frac{1}{|J(s_i, t_i)|} \left(-\frac{\partial N_a(s_i, t_i)}{\partial s} \frac{\partial x}{\partial t}(s_i, t_i) + \frac{\partial N_a(s_i, t_i)}{\partial t} \frac{\partial x}{\partial s}(s_i, t_i) \right)$$

Step 5 Evaluate the stiffness matrix

$$\mathbf{k}^{(e)} = t \iint_A \mathbf{B}^T \mathbf{D} \mathbf{B} |J| dA$$

$$\mathbf{k}^{(e)} = t \sum_{n=1}^{n_{\text{int}}} W_i \mathbf{B}^T(s_i, t_i) \mathbf{D}(s_i, t_i) \mathbf{B}(s_i, t_i) |J(s_i, t_i)|$$