

METHOD OF MOMENTS

used to solve operator equation (linear):

$$LF = g \quad (\text{deterministic problem})$$

we are dealing with F, g, h in a Hilbert space and thus define an inner product (F, g) such that: if $\alpha, \beta \in \mathbb{R}$, $F, g, h \in H$

$$\left\{ \begin{array}{l} (F, g) = (g, F) \\ (\alpha F + \beta g, h) = \alpha(F, h) + \beta(g, h) \\ (F^*, F) = \|F\|^2 > 0 \quad \text{if } F \neq 0 \\ \quad \quad \quad = 0 \quad \quad \quad \text{if } F = 0 \end{array} \right.$$

* \rightarrow complex conjugate

adjoint operator L^a : $(LF, g) = (F, L^a g)$

For all F in the domain of L

an operator is self-adjoint if $L^a = L$ and domain of L^a is that of L

i.e. $(LF, g) = (F, Lg)$

an operator is real if $LF(x) \in \mathbb{R}$ when $F(x) \in \mathbb{R}$

an operator is positive definite if:

$$(F^*, LF) > 0 \quad \forall F \neq 0$$

if solution to $LF = g$ exists and is unique for all g , then the inverse operator exists, L^{-1} , \exists

$$F = L^{-1}g$$

if g is known then this is the solution to original problem.

example: given $g(x)$ Find $F(x)$ $0 \leq x \leq 1$ \exists

$$(O.D.E) \quad -\frac{d^2 F}{dx^2} = g(x) \quad (B.C.'s) F(0) = F(1) = 0$$

$$L = -\frac{d^2}{dx^2}$$

, range of L is space of all fcn's g over $0 \leq x \leq 1$

, domain of L is the space of all fcn's F over $0 \leq x \leq 1$ satisfying B.C.'s and having second derivatives in the range of L

Note: both differential operator and boundary conditions define the operator.

Inner product: $(F, g) = \int_0^1 F(x)g(x) dx$

but could also use: $(F, g) = \int_0^1 w(x)F(x)g(x) dx$

$w(x) > 0$ (weighting F and g)

the adjoint operator L^a depends on the inner product which is used.

$$(LF, g) = \int_0^1 \left(-\frac{d^2 F}{dx^2}\right) g dx$$

using integration by parts: $\int u dv = uv - \int v du$

$$\begin{aligned}(LF, g) &= \int_0^1 g \left(-\frac{d^2 F}{dx^2}\right) dx = \int_0^1 \left(\frac{dF}{dx}\right) \frac{dg}{dx} dx - \left[\frac{dF}{dx} g\right]_0^1 \\ &= \int_0^1 F \left(-\frac{d^2 g}{dx^2}\right) dx + \left[F \frac{dg}{dx} - g \frac{dF}{dx}\right]_0^1\end{aligned}$$

last two terms are boundary terms and g on the boundary can be chosen so that these vanish. Then we have

$$(LF, g) = (F, L^a g)$$

$$L^a = -\frac{d^2}{dx^2} = L \quad \therefore L \text{ is self-adjoint}$$

notice domain of L^a is same as domain of L .

L is a real operator and is positive definite:

$$\begin{aligned} (F^*, LF) &= \int_0^1 F^* \left(-\frac{d^2 F}{dx^2} \right) dx = \int_0^1 \frac{dF^*}{dx} \frac{dF}{dx} dx - \left[F^* \frac{dF}{dx} \right]_0^1 \\ &= \int_0^1 \left| \frac{dF}{dx} \right|^2 dx > 0 \end{aligned}$$

inverse operator:

$$L^{-1}g = \int_0^1 G(x, x') g(x') dx'$$

$$G(x, x') = \begin{cases} x(1-x') & x < x' \\ (1-x)x' & x > x' \end{cases}$$

Note: since L is self-adjoint

$$(LF_1, F_2) = (F_1, LF_2) = (g_1, L^{-1}g_2) = (L^{-1}g_1, g_2)$$

and $\therefore L^{-1}$ is self-adjoint.

Approximations

now consider again : $LF = g$.

①

expand f in a series $f_1, f_2, f_3 \dots$ in $\mathcal{D}(L)$:

$$F = \sum_n \alpha_n f_n \quad \alpha_n \in \mathbb{R} \quad \text{②}$$

we call f_n expansion fns , or basis fns

if $\{f_n\}_1^\infty$ form a complete set of basis fns then we can represent the exact solution.

if $\{f_n\}_1^N$ is finite then we can determine an approximate solution.

$$LF = g = L\left(\sum_n \alpha_n f_n\right) = \sum_n \alpha_n Lf_n = g \quad \text{③}$$

we now define a set of weighting fns or

testing fns $\{w_m\}_1^M$ in the range of L .

and take inner product of ③ with each w_m :

$$\sum_n \alpha_n (w_m, Lf_n) = (w_m, g) \quad m = 1, 2, \dots \quad \text{④}$$

or in matrix form:

$$[l_{mn}] [\alpha_n] = [g_m] \quad \text{⑤}$$

$$[l_{mn}] = \begin{bmatrix} (w_1, L F_1) & (w_1, L F_2) & \dots \\ (w_2, L F_1) & (w_2, L F_2) & \dots \\ \vdots & \vdots & \ddots \end{bmatrix}$$

$$\alpha_n = \begin{bmatrix} \alpha_1 \\ \alpha_2 \\ \vdots \\ \alpha_n \end{bmatrix} \quad [g_m] = \begin{bmatrix} (w_1, g) \\ (w_2, g) \\ \vdots \\ (w_m, g) \end{bmatrix}$$

$$[\alpha_n] = [l_{mn}]^{-1} [g_m]$$

define : $[F_n]^T = [F_1 \ F_2 \ F_3 \ \dots]$

$$\therefore F = [F_n]^T [\alpha_n] = [F_n]^T [l_{mn}]^{-1} [g_m]$$

this is in general approximate.

if $w_n = F_n \Rightarrow$ Galerkin's method.

$\{F_n\}, \{w_n\}$ must be appropriately chosen.

- F_n in the domain of L
- w_n in the domain of L^a
- linear combination of F_n represent F
- " " " w_n " F^a

Example: $-\frac{d^2 F}{dx^2} = 1 + 4x^2 \quad 0 \leq x \leq 1$

$$F(0) = F(1) = 0$$

exact solution (integrate twice):

$$\frac{dF}{dx} = -\int (1 + 4x^2) dx = -x - \frac{4}{3}x^3 + A$$

$$F = \int \left(-x - \frac{4}{3}x^3 + A\right) dx = -\frac{1}{2}x^2 - \frac{1}{3}x^4 + Ax + B$$

$$F(0) = B = 0$$

$$F(1) = -\frac{1}{2} - \frac{1}{3} + A \Rightarrow A = \frac{5}{6}$$

$$F(x) = \frac{5x}{6} - \frac{x^2}{2} - \frac{x^4}{3}$$

moment method solution:

let $F_n = x - x^{n+1}$ (basis Fens) $n=1, 2, \dots, N$

$$F = \sum_{n=1}^N d_n (x - x^{n+1})$$

- we have chosen $F_n \in \mathcal{D}(L) \rightarrow L = -\frac{d^2}{dx^2}$
 $F(0) = F(1) = 0$

Apply Galerkin method: that is
choose weighting Fens as $w_n = F_n = x - x^{n+1}$

$w_n \in \mathcal{D}(L^a) = \mathcal{D}(L)$ since L is self-adjoint.

$$\sum_n \alpha_n (w_m, L F_n) = (w_m, 1+4x^2)$$

$$(w_m, L F_n) = \int_0^1 w_m L F_n dx = \int_0^1 (x-x^{m+1}) \left(-\frac{d^2}{dx^2} (x-x^{n+1}) \right) dx$$

$$= \int_0^1 (x-x^{m+1}) ((n+1)n x^{n-1}) dx$$

$$= \int_0^1 n(n+1) (x^n - x^{n+m}) dx = n(n+1) \left[\frac{x^{n+1}}{n+1} - \frac{x^{n+m+1}}{n+m+1} \right]_0^1$$

$$= n(n+1) \left[\frac{1}{n+1} - \frac{1}{n+m+1} \right] = n(n+1) \left[\frac{m}{(n+1)(n+m+1)} \right]$$

$$(w_m, L F_n) = \frac{nm}{n+m+1}$$

$$(w_m, 1+4x^2) = \int_0^1 (x-x^{m+1}) (1+4x^2) dx$$

$$= \int_0^1 x - x^{m+1} + 4x^3 - 4x^{m+3} dx$$

$$= \left[\frac{x^2}{2} - \frac{x^{m+2}}{m+2} + \frac{4x^4}{4} - \frac{4x^{m+4}}{m+4} \right]_0^1$$

$$= \frac{1}{2} - \frac{1}{m+2} + 1 - \frac{4}{m+4} = \frac{3}{2} - \frac{1}{m+2} - \frac{4}{m+4}$$

$$= \frac{3(m+2)(m+4) - 2(m+4) - 8(m+2)}{2(m+2)(m+4)} = \frac{3m^2 + m8}{2(m+2)(m+4)}$$

$$(w_m, 1+4x^2) = \frac{m(3m+8)}{2(m+2)(m+4)}$$

For $N=1$:

$$\alpha_1 \left(\frac{1}{3} \right) = \frac{11}{30} \quad \alpha_1 = \frac{11}{10} \quad F = \frac{11}{10} (x - x^2)$$

For $N=2$:

$$\begin{matrix} m=1 & \begin{matrix} n=1 & 2 \\ \frac{1}{3} & \frac{1}{2} \end{matrix} \\ 2 & \begin{matrix} \frac{1}{2} & \frac{4}{5} \end{matrix} \end{matrix} \quad \begin{matrix} \alpha_1 \\ \alpha_2 \end{matrix} = \begin{matrix} \frac{11}{30} \\ \frac{7}{12} \end{matrix} \quad \begin{matrix} m=1 \\ 2 \end{matrix} \quad \begin{matrix} \alpha_1 \\ \alpha_2 \end{matrix} = \begin{matrix} \frac{1}{10} \\ \frac{2}{3} \end{matrix}$$

$$F = \frac{1}{10} (x - x^2) + \frac{2}{3} (x - x^3)$$

$$F = \frac{23}{30} x - \frac{x^2}{10} - \frac{2}{3} x^3$$

For $N=3$:

$$\begin{matrix} \frac{1}{3} & \frac{1}{2} & \frac{3}{5} \\ \frac{1}{2} & \frac{4}{5} & 1 \\ \frac{3}{5} & 1 & \frac{9}{7} \end{matrix} \quad \begin{matrix} \alpha_1 \\ \alpha_2 \\ \alpha_3 \end{matrix} = \begin{matrix} \frac{11}{30} \\ \frac{7}{12} \\ \frac{51}{70} \end{matrix} \quad \underline{\alpha} = \begin{matrix} \frac{1}{2} \\ 0 \\ \frac{1}{3} \end{matrix}$$

$$F = \frac{1}{2} (x - x^2) + \frac{1}{3} (x - x^4)$$

$$F = \frac{5}{6} x - \frac{x^2}{2} - \frac{x^4}{3}$$

exact! since F_n
span the $\mathcal{P}(L)$

Note: $[l^{-1}]$ represents L^{-1}

example: solve the same problem

$$\begin{cases} -\frac{d^2 F}{dx^2} = 1 + 4x^2 & 0 \leq x \leq 1 \\ F(0) = F(1) = 0 \end{cases}$$

By the Rayleigh - Ritz variational method on the quadratic Functional for the problem. Use the same basis Fns.

$$I(F) = \int_0^1 \left(\frac{dF}{dx} \right)^2 dx - 2 \int_0^1 F(1+4x^2) dx$$

$$F = \sum_{n=1}^N \alpha_n F_n = [F_n]^T [\alpha_n] \quad F_n = x - x^{n+1}$$

$$\frac{dF}{dx} = \left[\frac{dF_n}{dx} \right]^T [\alpha_n] \quad F_n' = \frac{dF_n}{dx} = -(n+1)x^n$$

$$I(F) = \int_0^1 \left([F_n']^T [\alpha_n] \right)^2 dx - 2 \int_0^1 [F_n]^T [\alpha_n] (1+4x^2) dx$$

$$\frac{\partial I}{\partial \alpha_m} = 2 \int_0^1 ([F_n']^T [\alpha_n]) F_m' dx - 2 \int_0^1 F_m (1+4x^2) dx = 0$$

$$\int_0^1 ([F_n']^T [\alpha_n]) F_m' dx = \int_0^1 F_m (1+4x^2) dx$$

$$\int_0^1 [F_n']^T [\alpha_n] F_m' dx = \int_0^1 [F_n'] F_m' dx [\alpha_n]$$

$$\int u dv = uv - \int v du \quad (\text{partial integration})$$

$$\therefore \int_0^1 [F_n'] F_m' dx = [F_n'] F_m \Big|_0^1 - \int_0^1 F_m [F_n''] dx$$

the first term is zero since $F_m(0) = F_m(1) = 0$

$$\therefore \int_0^1 [F_n'] F_m' dx [\alpha_n] = - \int_0^1 F_m [F_n''] dx [\alpha_n]$$

Note this is the same as the Galerkin method

$$- \int_0^1 F_m [F_n''] dx [\alpha_n] = \sum_n \alpha_n (F_m, L F_n)$$

$$\int_0^1 F_m (1+4x^2) dx = (F_m, g)$$

\therefore Using Rayleigh-Ritz method for the minimization of $I(F)$ produces the

same matrix equation as applying

the Galerkin method.

$$\sum_n \alpha_n (F_m, L F_n) = (F_m, g)$$

Point Matching or Collocation

in the moment method we have

$$[d_{mn}] = [(w_m, Lf_n)]$$

$$[g_m] = (w_m, g)$$

$$(w_m, Lf_n) = \int_0^1 w_m Lf_n dv$$

if we choose $w_m = \delta(x - x_m)$

$$\begin{aligned} \text{then } \int_0^1 w_m Lf_n dv &= \int_0^1 Lf_n \delta(x - x_m) dv \\ &= (Lf_n) \Big|_{x=x_m} \end{aligned}$$

thus: integration is side-stepped. This is equivalent to requiring that

$$\sum_{n=1}^N d_n (Lf_n) = g$$

be satisfied exactly at N discrete points in the domain, hence the name point-matching.

example:
$$-\frac{d^2 u}{dx^2} = 1 + 4x^2 \quad u(0) = u(1) = 0 \quad (1)$$

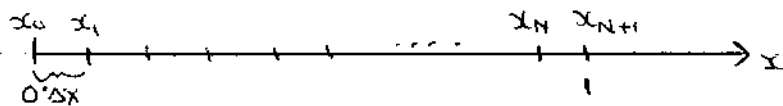
assume
$$u \approx \sum_{n=1}^N \alpha_n u_n \quad u_n = x - x^{n+1} \quad (\text{basis}) \quad (2)$$

$$L u = \sum_{n=1}^N \alpha_n \left(-\frac{d^2}{dx^2} (x - x^{n+1}) \right) = 1 + 4x^2$$

$$\sum_{n=1}^N \alpha_n (n+1)n x^{n-1} = 1 + 4x^2 \quad (3)$$

this represents 1 equation in N unknowns.

we now "match" this equation at N discrete points: (not on the boundary).



$$\Delta x = \frac{1}{N+1}$$

$$x_m = \frac{1}{N+1} m$$

$$\therefore \sum_{n=1}^N \alpha_n [n(n+1)] x_m^{n-1} = 1 + 4(x_m)^2 \quad m=1, 2, \dots, N$$

$$[l_{mn}] [\alpha_n] = [g_m]$$

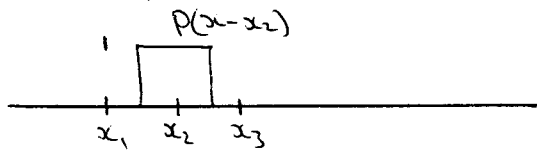
$$l_{mn} = n(n+1) \left(\frac{m}{N+1} \right)^{n-1}$$

$$g_m = 1 + 4 \left[\frac{m}{N+1} \right]^2$$

exercise: evaluate α_n for $n=1, 2, 3$ and compare to the Galerkin method.

Method of Subsections

a) use "pulse" fns for basis fns.



$$\Delta x = \frac{1}{N+1}$$

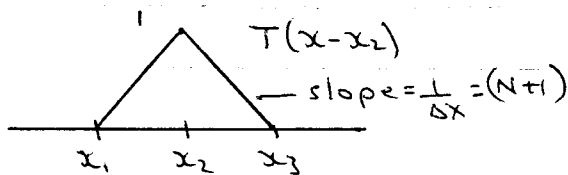
$$x_n = \frac{n}{N+1}$$

$$P_n = P(x-x_n) = \begin{cases} 1 & |x-x_n| \leq \frac{1}{2(N+1)} = \frac{\Delta x}{2} \\ 0 & |x-x_n| \geq \frac{1}{2(N+1)} = \frac{\Delta x}{2} \end{cases} \quad (1)$$

expanding:

$$u(x) = \sum_{n=1}^N \alpha_n P(x-x_n) \quad (2)$$

b) "Triangle" fns for basis \Rightarrow piecewise linear approximation

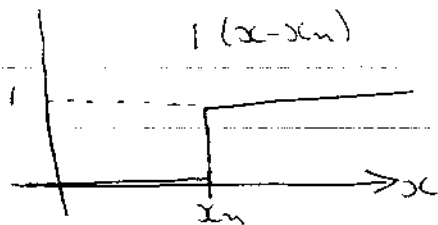


$$T_n = T(x-x_n) = \begin{cases} 1 - |x-x_n|(N+1) & |x-x_n| < \frac{1}{N+1} = \Delta x \\ 0 & |x-x_n| > \frac{1}{N+1} = \Delta x \end{cases} \quad (3)$$

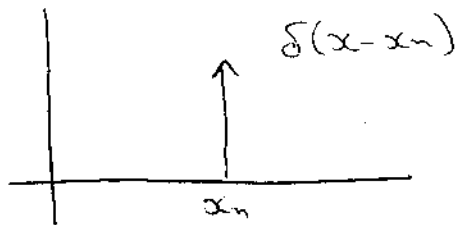
$$u(x) = \sum_{n=1}^N \alpha_n T(x-x_n) \quad (4)$$

if we are using the expansions ② or ④ to approximate a function satisfying a differential equation then we will have to determine derivatives of P_n and T_n .

consider the unit step fcn:

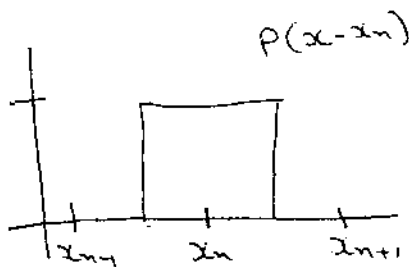


$$1(x-x_n) = \begin{cases} 1 & x \geq x_n \\ 0 & x < x_n \end{cases}$$

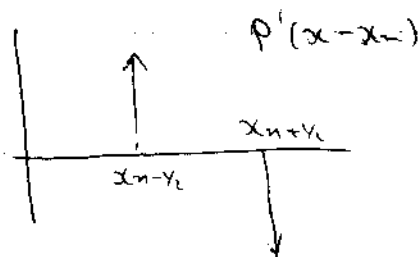


$$1'(x-x_n) = \delta(x-x_n) = \begin{cases} \infty & x = x_n \\ 0 & x \neq x_n \end{cases}$$

For pulse



$$P_n = P(x-x_n) = 1(x-x_{n-1/2}) - 1(x-x_{n+1/2})$$

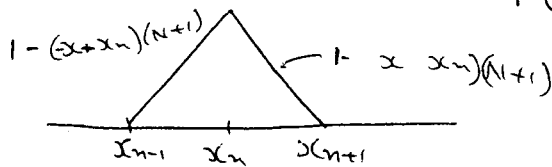


$$\frac{d}{dx} P(x-x_n) = \frac{d}{dx} [1(x-x_{n-1/2}) - 1(x-x_{n+1/2})]$$

$$P'(x-x_n) = \delta(x-x_{n-1/2}) - \delta(x-x_{n+1/2})$$

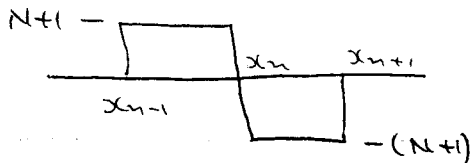
Note: second derivative doesn't exist

Triangle fcn:



$$|x-x_n| < \frac{1}{N+1} = \Delta x$$

$$T(x-x_n) = \begin{cases} 1 - |x-x_n|(N+1) & |x-x_n| < \frac{1}{N+1} \\ 0 & |x-x_n| > \frac{1}{N+1} \end{cases}$$



$$\begin{aligned} T'(x-x_n) &= (N+1) [1(x-x_{n-1}) - 1(x-x_n)] \\ &\quad - (N+1) [1(x-x_n) - 1(x-x_{n+1})] \\ &= (N+1) [1(x-x_{n-1}) - 2 \cdot 1(x-x_n) + 1(x-x_{n+1})] \end{aligned}$$

$$\frac{d^2 T(x-x_n)}{dx^2} = (N+1) [\delta(x-x_{n-1}) - 2\delta(x-x_n) + \delta(x-x_{n+1})]$$

example:

$$-\frac{d^2 u}{dx^2} = 1+x^2$$

$$u(0) = u(1) = 0$$

$$u = \sum_{n=1}^N \alpha_n T(x-x_n)$$

Note: boundary conditions are automatically satisfied.

$$-\frac{d^2 u}{dx^2} = \sum_{n=1}^N \alpha_n \left(-\frac{d^2}{dx^2} T(x-x_n) \right)$$

$$= \sum_{n=1}^N \alpha_n \left[-(N+1) [\delta(x-x_{n-1}) - 2\delta(x-x_n) + \delta(x-x_{n+1})] \right]$$

$$\sum_{n=1}^N \alpha_n (N+1) [-\delta(x-x_{n-1}) + 2\delta(x-x_n) - \delta(x-x_{n+1})] = 1+x^2$$

we can now choose P_n as test fens
(or weighting fens)

$$\begin{aligned} \therefore \sum_{n=1}^N \alpha_n (N+1) \int_0^1 P(x-x_m) [-\delta(x-x_{n-1}) + 2\delta(x-x_n) - \delta(x-x_{n+1})] dx \\ = \int_0^1 P(x-x_m) (1+4x^2) dx \end{aligned}$$

$$\therefore l_{mn} = \begin{cases} 2(N+1) & \text{for } m=n \\ -(N+1) & \text{for } |m-n|=1 \\ 0 & \text{for } |m-n|>1 \end{cases}$$

$$g_m = \int_{x_{m-1/2}}^{x_{m+1/2}} (1+4x^2) dx = \left[x + \frac{4}{3}x^3 \right]_{x_{m-1/2}}^{x_{m+1/2}}$$

$$= \frac{1}{N+1} (m+\frac{1}{2}) + \frac{4}{3} \frac{(m+\frac{1}{2})^3}{(N+1)^3} - \frac{1}{N+1} (m-\frac{1}{2}) - \frac{4}{3} \frac{(m-\frac{1}{2})^3}{(N+1)^3}$$

$$= \frac{1}{N+1} \left[1 + \frac{4}{3} \frac{(m+\frac{1}{2})^3 - (m-\frac{1}{2})^3}{(N+1)^2} \right]$$

$$= \frac{1}{N+1} \left[1 + \frac{4}{(N+1)^2} \left(m^2 + \frac{1}{3} \right) \right]$$

exercise: check for $N=1, 2, 3$.