

A Constant 3-fold Autoconvolution

An experimental approach to numerically estimating the supremum of the 3-fold autoconvolution for functions $\|f\|_1 = 1$.

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- “A symmetric subset of the reals is one that remains invariant under some reflection $x \rightarrow c - x$. We consider, for any $0 < \epsilon \leq 1$, the largest real number $\Delta(\epsilon)$ such that every subset of $[0, 1]$ with measure greater than ϵ contains a symmetric subset with measure $\Delta(\epsilon)$.” [Martin & O’Byrant 2007]
- Discrete problem [Green 2001]: a set S of integers is called a $B^*[g]$ set if for any given m there are at most g ordered pairs $(s_1, s_2) \in S \times S$ with $s_1 + s_2 = m$.
- Interest: estimating $\Delta(\epsilon)$ or the cardinality of $B^*[g]$ sets
- $\inf_{f \in C^0(-1,1)} \|f * f * f\|_\infty$, subject to $\|f\|_1 = 1$

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- In [Martin & O'Bryant 2007], a bound is obtained:

$$\inf_{f \in C^0(-1,1)} \frac{\|f * f * f\|_\infty}{\|f\|_1} \approx 0.2873\dots$$

- Since a constant function has minimal infinity-norm, this is equivalent to calculating:
- Find $f \in C^0(-1, 1)$ such that $f * f * f = 1$ on $[-1, 1]$.
- Previous work's estimate is based on:

$$K_3(x) = \begin{cases} 1, & 0 \leq |x| \leq 1, \\ 0.6644 + 0.3356 \left(\frac{2}{\pi} \tan^{-1} \left(\frac{1-x/2}{\sqrt{x-1}} \right) \right)^{1.2015}, & 1 \leq |x| \leq 2. \end{cases}$$

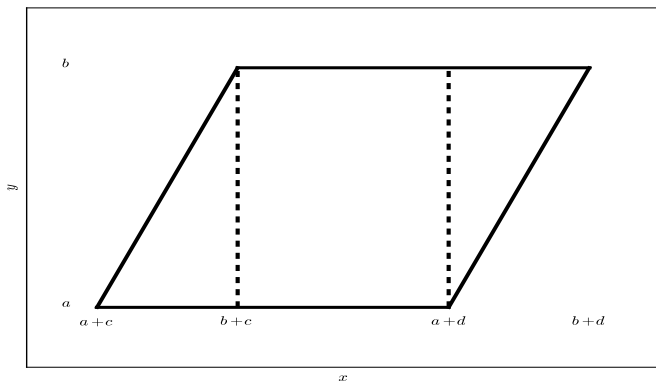
- Where is the intuition? How can we systematically improve?

- Experimental mathematics: use principles of numerical analysis to guide the construction of a good algorithm
 - Systematic & general
 - Symmetry and convolution properties to reduce complexity
 - Exponential convergence \leftrightarrow geometric decay in approximation's coefficients
- To build intuition
 - Use a general & universal software package for computing with functions. Chebfun!
 - Since f is defined on an interval, a Chebyshev interpolant is a good place to begin
- Outcome
 - Convincing numerical evidence for convergence
 - Optimized Julia code using [DEQuadrature.jl](#) and [ApproxFun.jl](#)
 - High accuracy approximation

Convolution

For integrable f compactly supported on $[a, b]$ and integrable g on $[c, d]$, convolution is defined as:

$$(f * g)(x) = \int_{\max(a, x-d)}^{\min(b, x-c)} f(y)g(x-y) dy.$$



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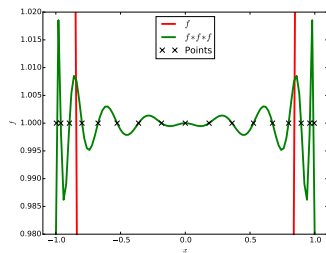
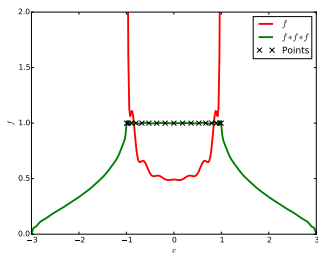
$$(f * g)(x) = \int_{\max(a, x-d)}^{\min(b, x-c)} f(y)g(x-y) dy.$$

The parallelogram of the convolution domain can be explicitly written:

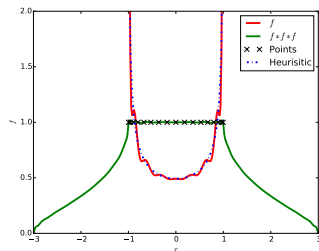
$$(f * g)(x) = \begin{cases} \int_a^{x-c} f(y)g(x-y) dy, & x \in [a+c, b+c], \\ \int_a^b f(y)g(x-y) dy, & x \in [b+c, a+d], \\ \int_{x-d}^b f(y)g(x-y) dy, & x \in [a+d, b+d]. \end{cases}$$

Straightforward modifications for functions on open intervals.

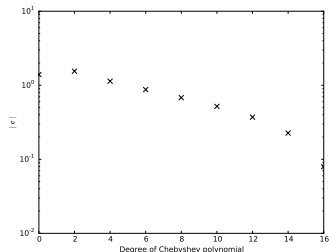
Using Chebfun, we collocate at Chebyshev roots to remove possibility of Runge's phenomenon:



- Oscillations on the order of 2% \Rightarrow a generalized Gibbs phenomenon
- This could imply the function is singular at the endpoints



Conjecture



Coefficients

- We see an algebraic decay in the coefficients \Rightarrow a poor approximation
- Since convolution is smoothing, f can have endpoint exponents as low as $-2/3$ for $f * f * f \in C^0[-3, 3]$
- Conjecture: $f(x) = \frac{g(x)}{\sqrt{1-x^2}}$ for some analytic g .

Convoluting with Singularities

- Chebfun has a very efficient algorithm for convolution of Chebyshev series [Hale & Townsend 2014]
 - Convert Chebyshev to Legendre coefficients with $\mathcal{O}(N \log^2 N / \log \log N)$ complexity
 - Use recurrences derived from spherical Bessel functions to convolve with $\mathcal{O}((M + N)^2)$ complexity
 - Revert to Chebyshev coefficients
- Significantly cheaper than quadrature with $\mathcal{O}((M + N)^3)$ complexity
- However, the algorithm is not applicable to functions with endpoint singularities
- Challenge comes from Jacobi elliptic integral of the first kind:

$$\left(\frac{1}{\sqrt{1-x^2}} * \frac{1}{\sqrt{1-x^2}} \right) (x) = \Re \frac{{}_2F_1(i\sqrt{4-x^2}/x, ix/\sqrt{4-x^2})}{i\sqrt{4-x^2}} \\ \sim \log |8/x|, \quad \text{as } x \rightarrow 0.$$

- The trapezoidal rule $\int_a^b f(x) dx \approx (b-a) \left[\frac{f(a) + f(b)}{2} \right]$.
- The composite version $T(h) = h \sum_{k=1}^{n-1} \frac{f(x_{k-1}) + f(x_k)}{2}$, where $h = \frac{b-a}{n}$ and $x_k = a + k h$.
- Euler-Maclaurin summation formula:
$$T(h) - \int_a^b f(x) dx \sim \sum_{l=1}^{\infty} h^{2l} \frac{B_{2l}}{(2l)!} \left(f^{(2l-1)}(b) - f^{(2l-1)}(a) \right), \quad \text{as } h \rightarrow 0.$$
- If f is periodic, or if $f^{(n)}(\cdot) \rightarrow 0$ at endpoints, the convergence is faster than any power of h .
- Variable transformations $\phi : \mathbb{R} \rightarrow (a, b)$ with exponential decay [Stenger 1973] and [Takahasi & Mori 1974].

Quadrature by Variable Transformation

Consider the integral:

$$\int_a^b f(x) dx = \int_{-\infty}^{+\infty} f(\phi(t))\phi'(t) dt.$$

Variable transformations which induce single exponential endpoint decay are:

$$x = \phi_{\text{SE}}(t) = \frac{a+b}{2} + \left(\frac{b-a}{2}\right) \tanh(t/2),$$

$$dx = \phi'_{\text{SE}}(t) dt = \left(\frac{b-a}{4}\right) \operatorname{sech}^2(t/2) dt,$$

Double exponential endpoint decay are:

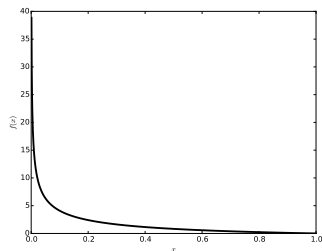
$$x = \phi_{\text{DE}}(t) = \frac{a+b}{2} + \left(\frac{b-a}{2}\right) \tanh\left(\frac{\pi}{2} \sinh t\right),$$

$$dx = \phi'_{\text{DE}}(t) dt = \left(\frac{b-a}{2}\right) \operatorname{sech}^2\left(\frac{\pi}{2} \sinh t\right) \frac{\pi}{2} \cosh t dt.$$

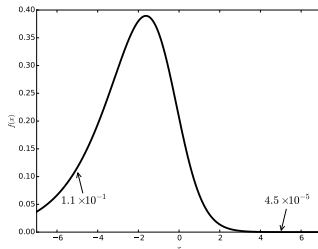
Quadrature by Variable Transformation

Example [Mori & Sugihara 2001]:

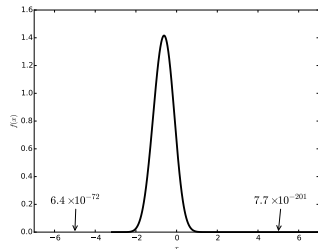
$$\int_0^1 x^{-1/4} \log(1/x) dx = 16/9.$$



Integrand

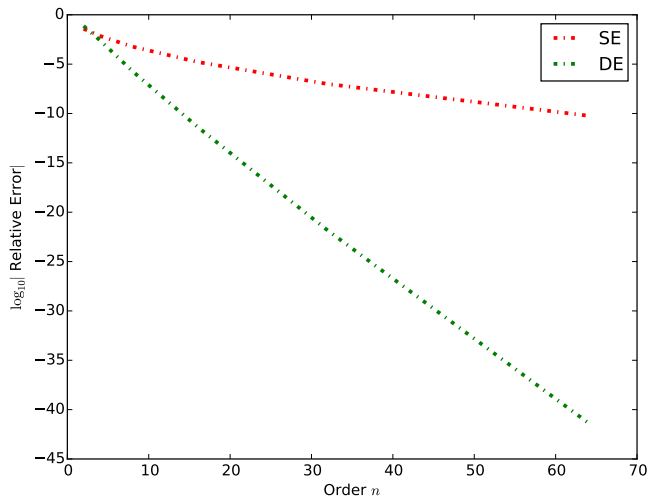


SE transformation



DE transformation

Quadrature by Variable Transformation



How to determine step size h for composite rule on \mathbb{R} ?

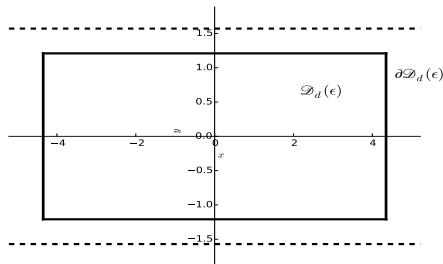
Quadrature by Variable Transformation

Let d be a positive number and let $\mathcal{D}_d = \lim_{\epsilon \rightarrow 0} \mathcal{D}_d(\epsilon)$ denote the strip region of width $2d$ about the real axis:

$$\mathcal{D}_d(\epsilon) = \{z \in \mathbb{C} : |\operatorname{Re} z| < \epsilon^{-1}, \quad |\operatorname{Im} z| < d(1 - \epsilon)\}.$$

Let $B(\mathcal{D}_d)$ be the family of functions such that:

$$\mathcal{N}_1(f, \mathcal{D}_d) = \lim_{\epsilon \rightarrow 0} \int_{\partial \mathcal{D}_d(\epsilon)} |f(z)| dz < +\infty.$$



Let $\omega(z)$ be a non-vanishing function defined on \mathcal{D}_d , and let:

$$H^\infty(\mathcal{D}_d, \omega) = \{f : \mathcal{D}_d \rightarrow \mathbb{C} \mid f(z) \text{ is analytic in } \mathcal{D}_d, \text{ and } \|f\| < +\infty\},$$

where the norm is given by:

$$\|f\| = \sup_{z \in \mathcal{D}_d} \left| \frac{f(z)}{\omega(z)} \right|.$$

Let $\mathcal{E}_{N,h}^T(H^\infty(\mathcal{D}_d, \omega))$ denote the error norm in $H^\infty(\mathcal{D}_d, \omega)$:

$$\mathcal{E}_{N,h}^T(H^\infty(\mathcal{D}_d, \omega)) = \sup_{\substack{f \in H^\infty(\mathcal{D}_d, \omega) \\ \|f\| \leq 1}} \left| \int_{-\infty}^{+\infty} f(x) dx - h \sum_{k=-n}^{+n} f(kh) \right|.$$

Theorem [Sugihara 1997]

Suppose:

- 1 $\omega(z) \in B(\mathcal{D}_d)$;
- 2 $\omega(z)$ does not vanish at any point in \mathcal{D}_d and takes real values on the real axis;
- 3 $\alpha_1 \exp(-\beta|x|) \leq |\omega(x)| \leq \alpha_2 \exp(-\beta|x|)$, $x \in \mathbb{R}$,
where α_1, α_2 , and $\beta > 0$.

Then:

$$\mathcal{E}_{N,h}^T(H^\infty(\mathcal{D}_d, \omega)) \leq C_{d,\omega} \exp\left(-(\pi d \beta N)^{1/2}\right),$$

where $N = 2n + 1$, the mesh size h is chosen optimally as:

$$h = \sqrt{\frac{2\pi d}{\beta n}},$$

and $C_{d,\omega}$ is a constant depending on d and ω .

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where $\alpha_1, \alpha_2, \beta_1, \beta_2, \gamma > 0$.

Then:

$$\mathcal{E}_{N,h}^T(H^\infty(\mathcal{D}_d, \omega)) \leq C_{d,\omega} \exp\left(-\frac{\pi d \gamma N}{\log(\pi d \gamma N / \beta_2)}\right),$$

where $N = 2n + 1$, the mesh size h is chosen optimally as:

$$h = \frac{\log(2\pi d \gamma n / \beta_2)}{\gamma n},$$

and $C_{d,\omega}$ is a constant depending on d and ω .

Nonexistence Theorem [Sugihara 1997]

There exists no function $\omega(z)$ that satisfies at once:

- 1 $\omega(z) \in B(\mathcal{D}_d)$;
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- 3 $\omega(x) = \mathcal{O}(\exp(-\beta e^{\gamma|x|}))$ as $|x| \rightarrow \infty$, where $\beta > 0$, and $d\gamma > \pi/2$.

Outcome:

- Optimality of the DE transformation for the trapezoidal rule.

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Outcome:

- Optimality of the DE transformation for the trapezoidal rule.
- What happens when complex singularities are present?

Maximizing the Convergence Rate

Problem [Slevinsky & Olver 2015]: How can we maximize the convergence rate of the trapezoidal rule:

$$\int_{-\infty}^{\infty} f(\phi(t))\phi'(t) dt \approx h \sum_{k=-n}^{+n} f(\phi(kh))\phi'(kh),$$

despite the singularities of $f \in \mathbb{C}$? Let

$$\Phi_{\text{ad}} = \left\{ \begin{array}{l} \phi : f(\phi(t))\phi'(t) \in H^\infty(\mathcal{D}_d, \omega) \text{ for some } d > 0, \\ \text{and for some } \omega \text{ such that:} \\ 1. \ \omega(z) \in B(\mathcal{D}_d); \\ 2. \ \omega(z) \text{ does not vanish at any point in } \mathcal{D}_d \\ \text{and takes real values on the real axis;} \\ 3. \ \alpha_1 \exp(-\beta_1 e^{\gamma|x|}) \leq |\omega(x)| \leq \alpha_2 \exp(-\beta_2 e^{\gamma|x|}), \\ x \in \mathbb{R}, \text{ where } \alpha_1, \alpha_2, \beta_1, \beta_2, \gamma > 0. \end{array} \right\}$$

Maximizing the Convergence Rate

Then we wish to find $\phi \in \Phi_{\text{ad}}$ such that the convergence rate is maximized:

$$\underbrace{\operatorname{argmax}_{\phi \in \Phi_{\text{ad}}} \left(\frac{\pi d \gamma N}{\log(\pi d \gamma N / \beta_2)} \right)}_{\text{Trapezoidal Convergence Theorem}} \quad \text{subject to} \quad \underbrace{d \gamma \leq \frac{\pi}{2}}_{\text{Nonexistence Theorem}}$$

Result: an infinite-dimensional optimization problem for ϕ .
Consider the asymptotic problem as $N \rightarrow \infty$:

$$\begin{aligned} \frac{\pi d \gamma N}{\log(\pi d \gamma N / \beta_2)} &= \frac{\pi d \gamma N}{\log N + \log(\pi d \gamma / \beta_2)}, \\ &\sim \frac{\pi d \gamma N}{\log N}, \quad \text{as } N \rightarrow \infty. \end{aligned}$$

- We maximize the convergence rate when $d \gamma = \pi/2$
- Numerical algorithm is the subject of [Slevinsky & Olver 2015]

Return to Convolution

Let $\mathbf{c} = [c_1, c_2, \dots, c_{\lceil N/2 \rceil}]^T$, $w(x) = (1 - x^2)^\lambda$, and x_i the $\lceil N/2 \rceil$ nonnegative roots of $T_N(x)$. Then:

$$g(\mathbf{c}, x_i) = \text{conv}(\mathbf{c}^T T_{0:2:N} w, \text{conv}(\mathbf{c}^T T_{0:2:N} w, \mathbf{c}^T T_{0:2:N} w))(x_i) - 1,$$

Newton iteration is the most efficient nonlinear solver.

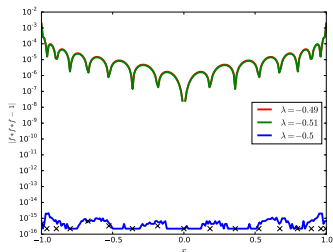
By commutativity and associativity of convolution, we have:

$$[J(g)]_{i,j} = 3 \text{conv}(T_{2j-2} w, \text{conv}(\mathbf{c}^T T_{0:2:N} w, \mathbf{c}^T T_{0:2:N} w))(x_i).$$

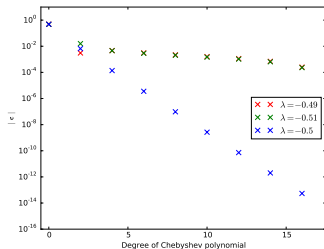
For each point x_i , we pre-compute the inner autoconvolution, and $[J(g)]_{i,j}$ can be computed in the cost of only 2 integrals (parallelogram overlap). By linearity of convolution, g is simply:

$$g(\mathbf{c}, x_i) = \frac{1}{3} J(g) \mathbf{c} - 1.$$

DE Convolution & Numerical Evidence for Conjecture



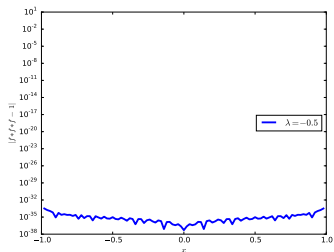
Convolution



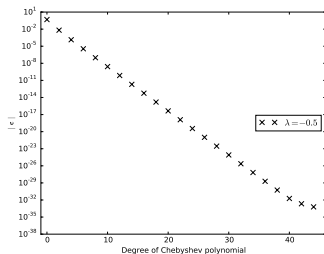
Coefficients

Algorithmic complexity scales as $\mathcal{O}(n^2 N^2)$ where:

- n is the number of quadrature nodes
- N is the number of coefficients
- 101 quadrature nodes and 9 coefficients takes ≈ 0.1 seconds per Newton iteration in double precision



Convolution



Coefficients

Algorithmic complexity scales as $\mathcal{O}(n^2 N^2)$ where:

- n is the number of quadrature nodes
- N is the number of coefficients
- 1001 quadrature nodes and 23 coefficients takes ≈ 3 hours per Newton iteration in extended precision

- A simple & systematic representation is conjectured for the continuous function whose 3-fold autoconvolution is constant
- Geometric convergence is observed with inverse square root endpoint singularities with $\mathcal{O}(n^2 N^2)$ complexity
- Previous result [Martin & O'Bryant 2007]:

$$\inf_{f \in C^0(-1,1)} \frac{\|f * f * f\|_\infty}{\|f\|_1} \approx 0.287\ 3\dots$$

- New result:

$$\inf_{f \in C^0(-1,1)} \frac{\|f * f * f\|_\infty}{\|f\|_1} \approx 0.287\ 319\ 803\ 575\ 759\ 796\ 363\ 627\ 713\ 763\ 526\dots$$

- Is the function simple or can we determine a closed-form for the coefficients?
 - The ratio of successive coefficients may offer some insight
 - PSLQ may detect a simple representation for the constants

Thank you all very much for your time!

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- 6 F. Stenger. *J. Inst. Math. Appl.*, 12:103–114, 1973.
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